

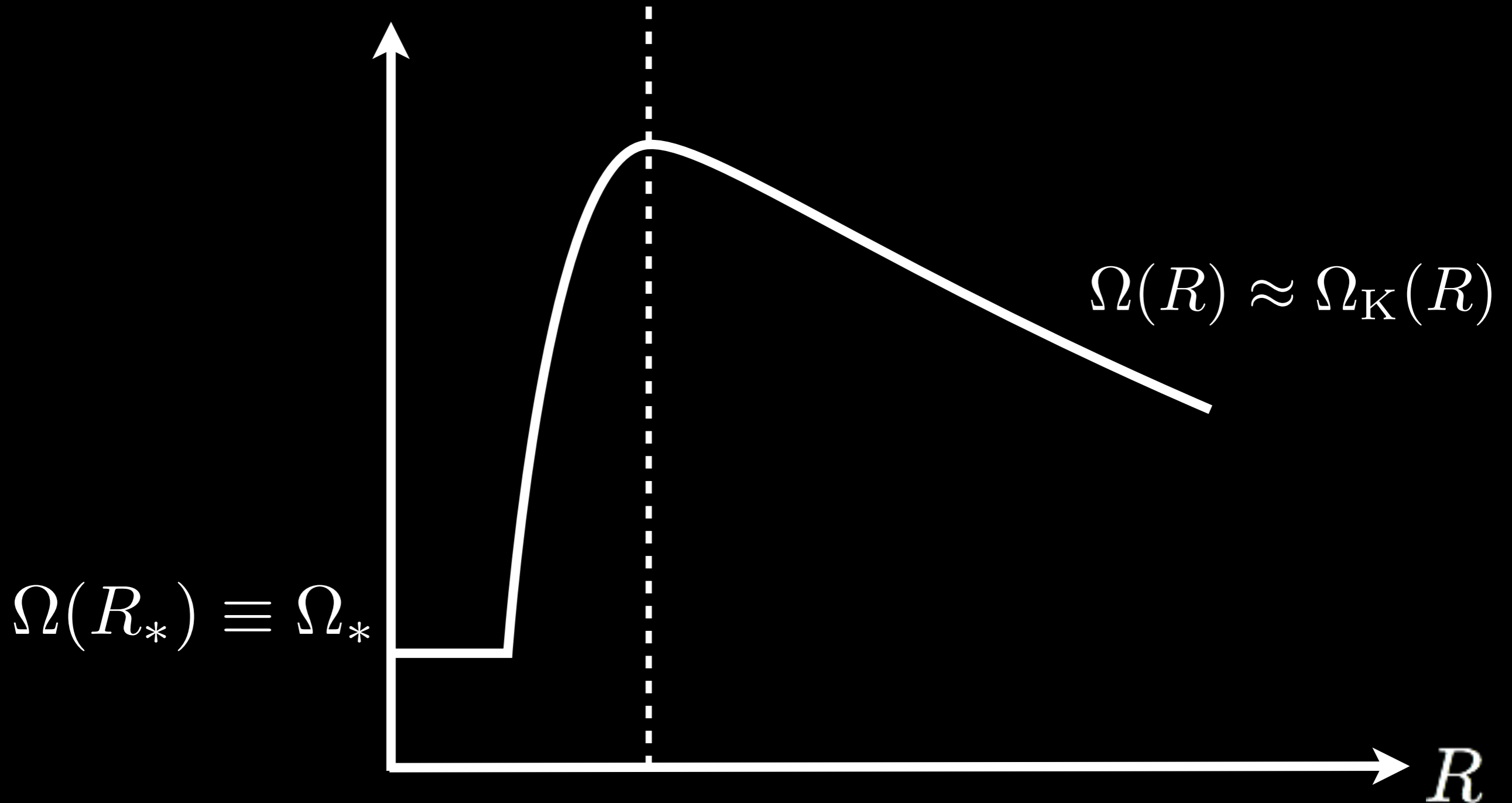
# On Angular Momentum Transport in Accretion Disk Boundary Layers Around Weakly Magnetized Stars



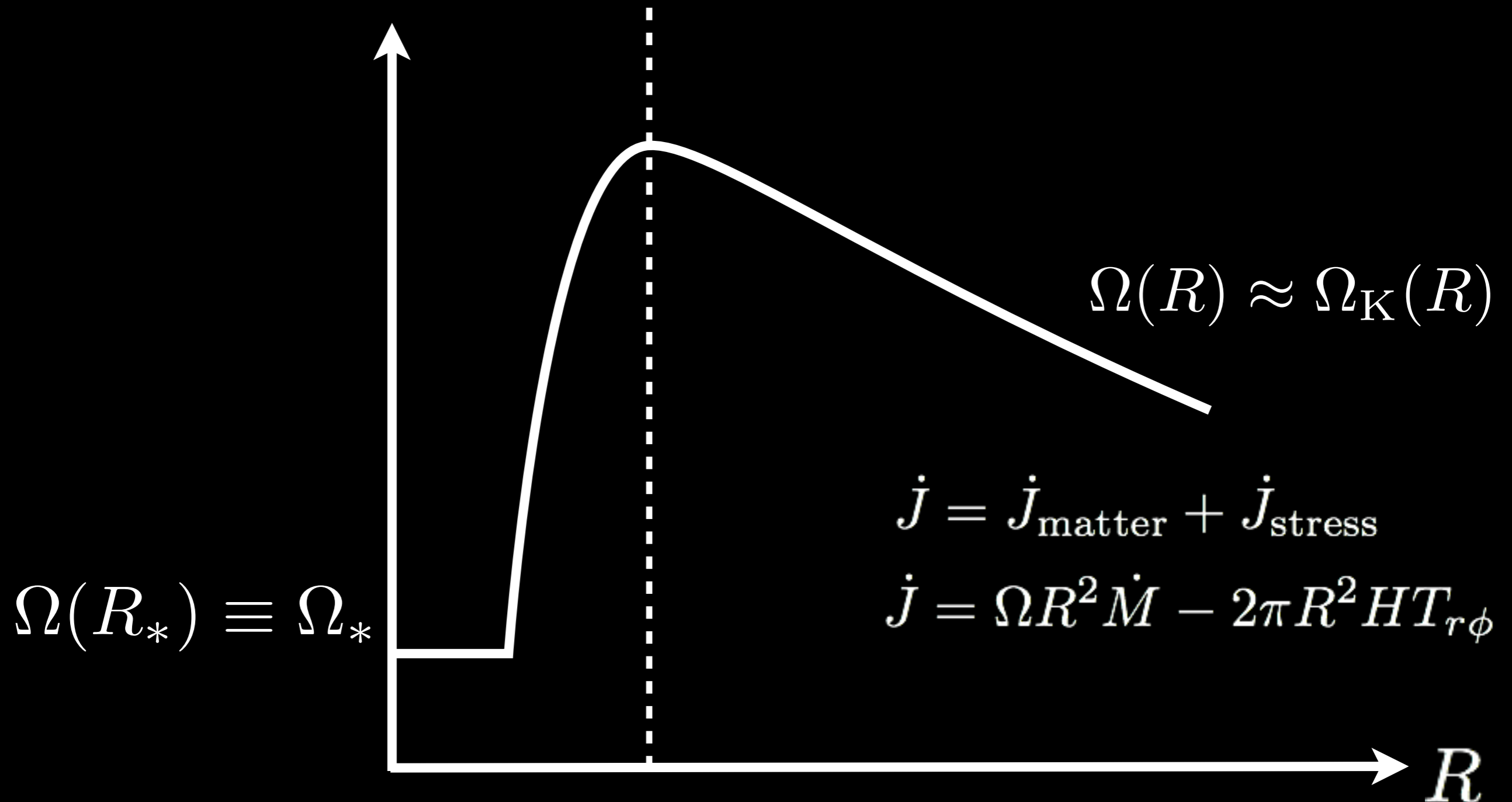
Martin E. Pessah (NBI) + Chi-kwan Chan (NORDITA) – ApJ, 751, 48, 2012

# Standard Picture of the BL

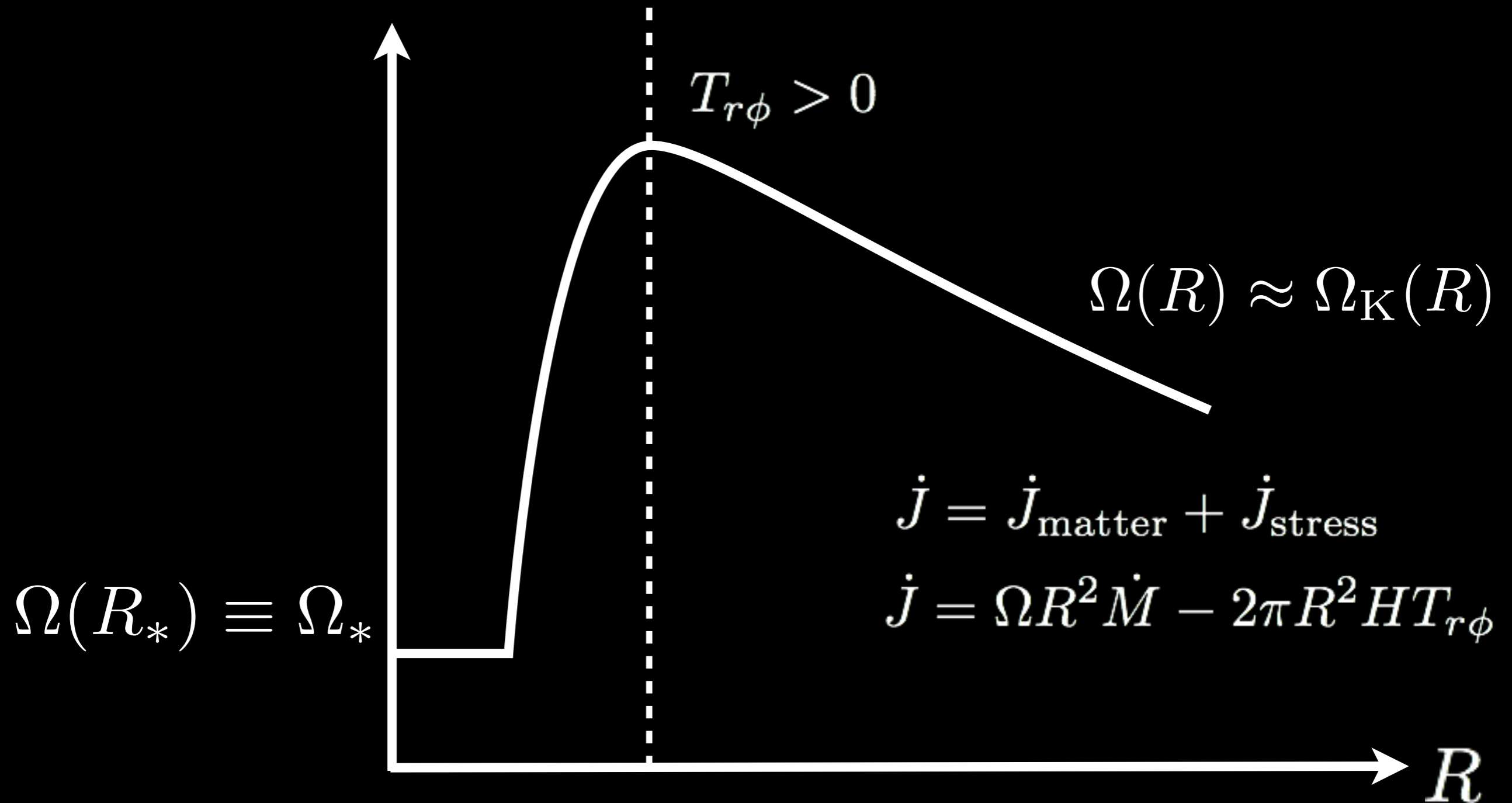
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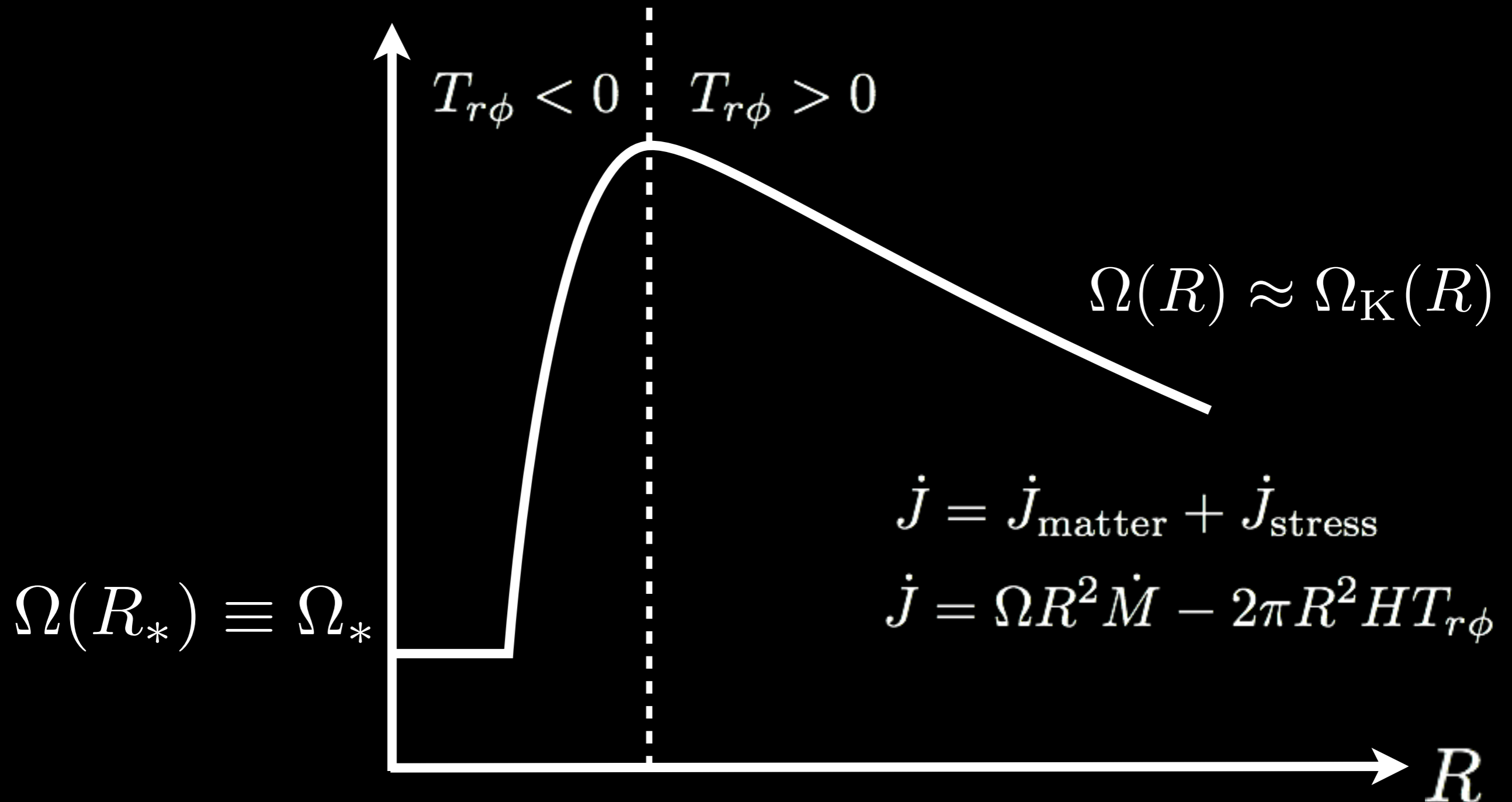
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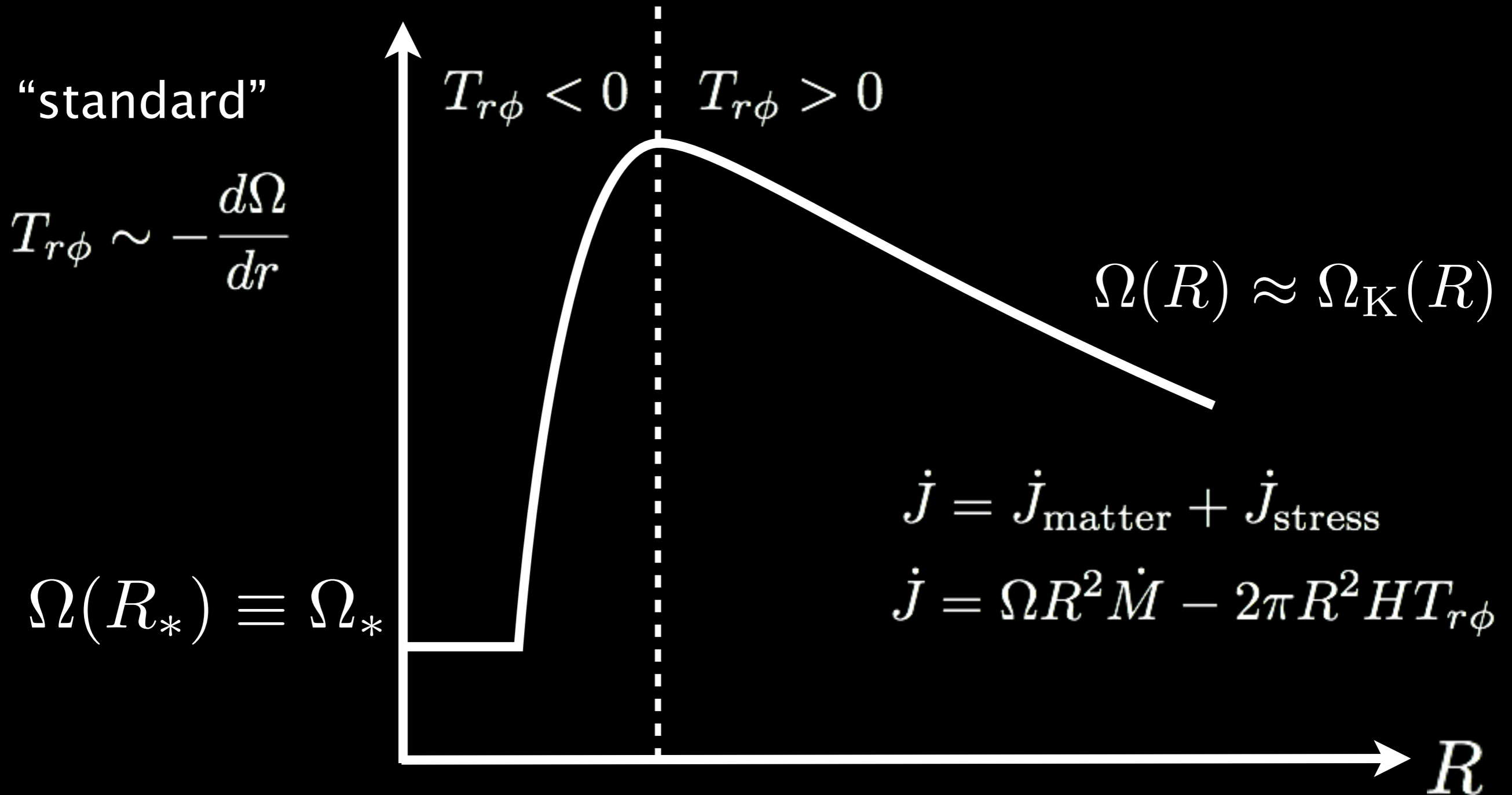
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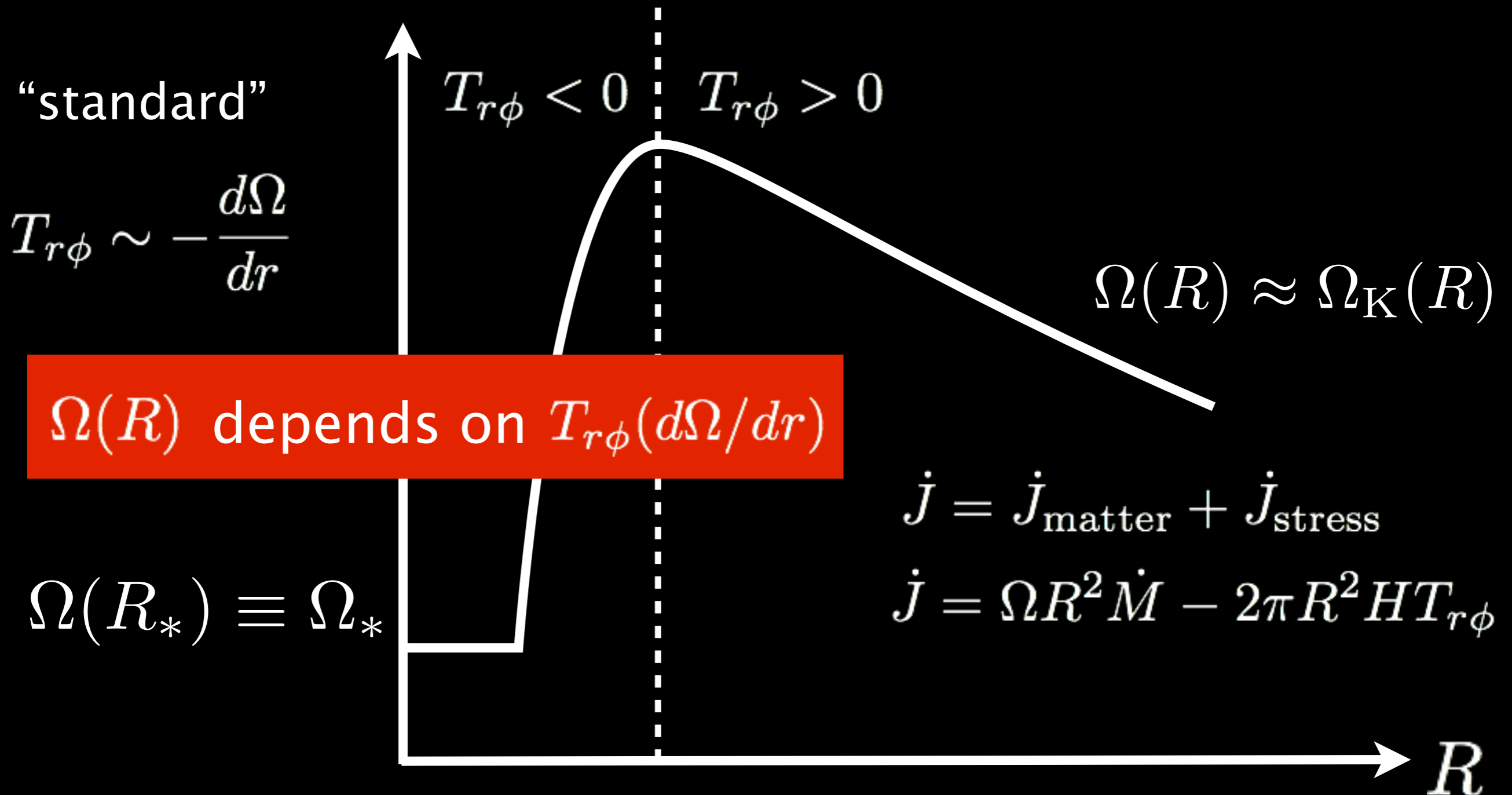
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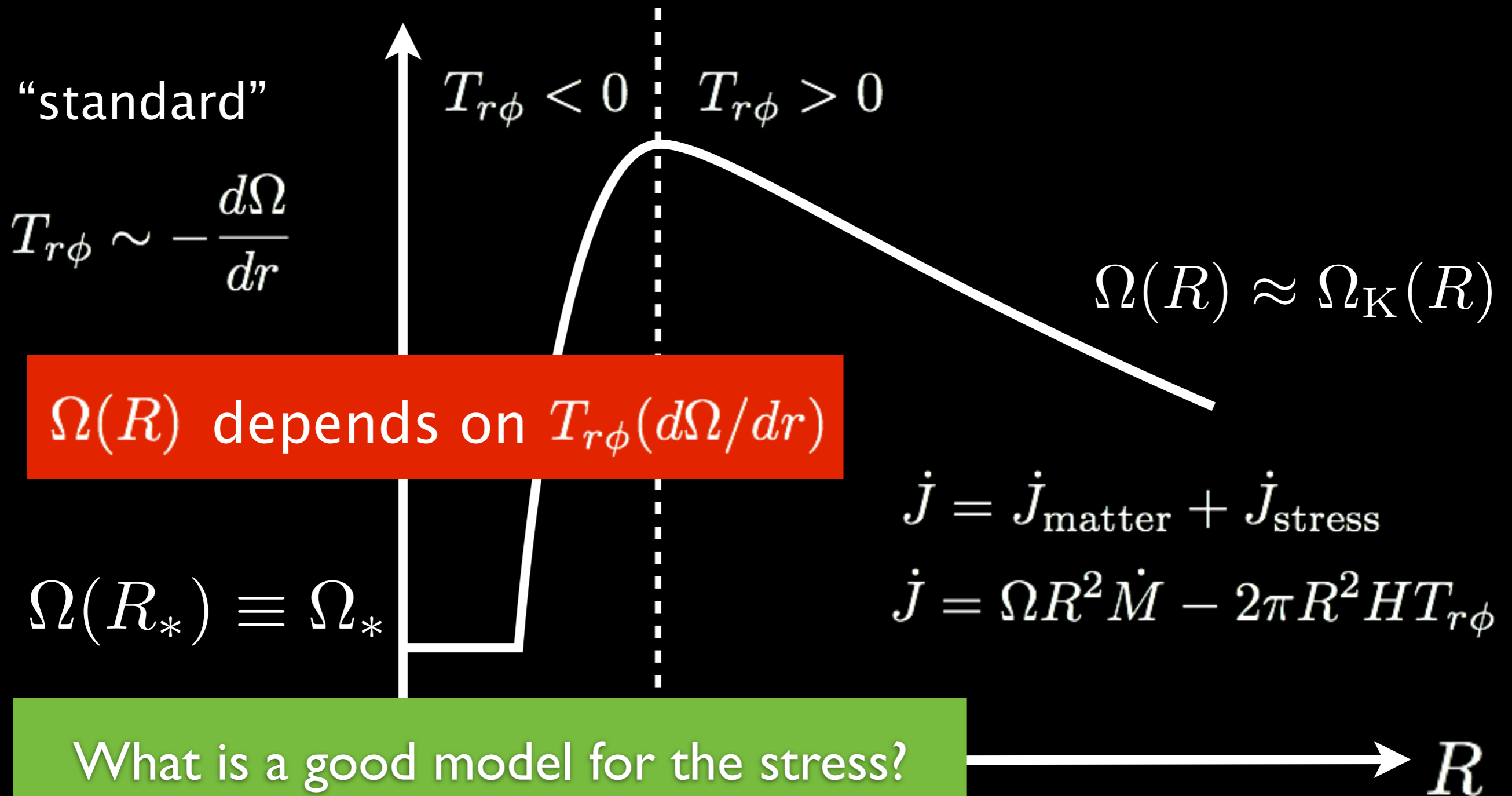
# Standard Picture of the BL



# Standard Picture of the BL



# Standard Picture of the BL





# Standard Accretion Disk Model

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- ✦ Shakura & Sunyaev (1973)
- ✦ “The efficiency of the mechanism of **angular momentum transport** is characterized by **parameter**”

$$\alpha = \frac{v_{\text{turb}}}{c_s} + \frac{B^2}{4\pi\rho c_s^2}$$

- ✦ In terms of **stress**,

$$T_{r\phi} \equiv R_{r\phi} - M_{r\phi} \sim \alpha P$$

# But...

---

- ✦ Shakura & Sunyaev (1973) **considered Keplerian** flow
- ✦ **Shear-dependent** turbulent viscosity – not addressed
- ✦ All later works **assume Newtonian** turbulent viscosity

$$\nu = \alpha c_s H = \alpha c_s^2 R / v_\phi$$

$$T_{r\phi} = \alpha q \Sigma c_s^2 \quad q \equiv -d \ln \Omega / d \ln R$$

- ✦ Is **Newtonian** turbulent viscosity a **good** assumption?

# Standard Calculation

---

❖ Assume **steady state**

❖ Continuity equation  $\Rightarrow$  constant accretion rate

$$\dot{M} = -2\pi R \Sigma v_R = \text{constant}$$

❖ Angular momentum equation  $\Rightarrow$  flux balance

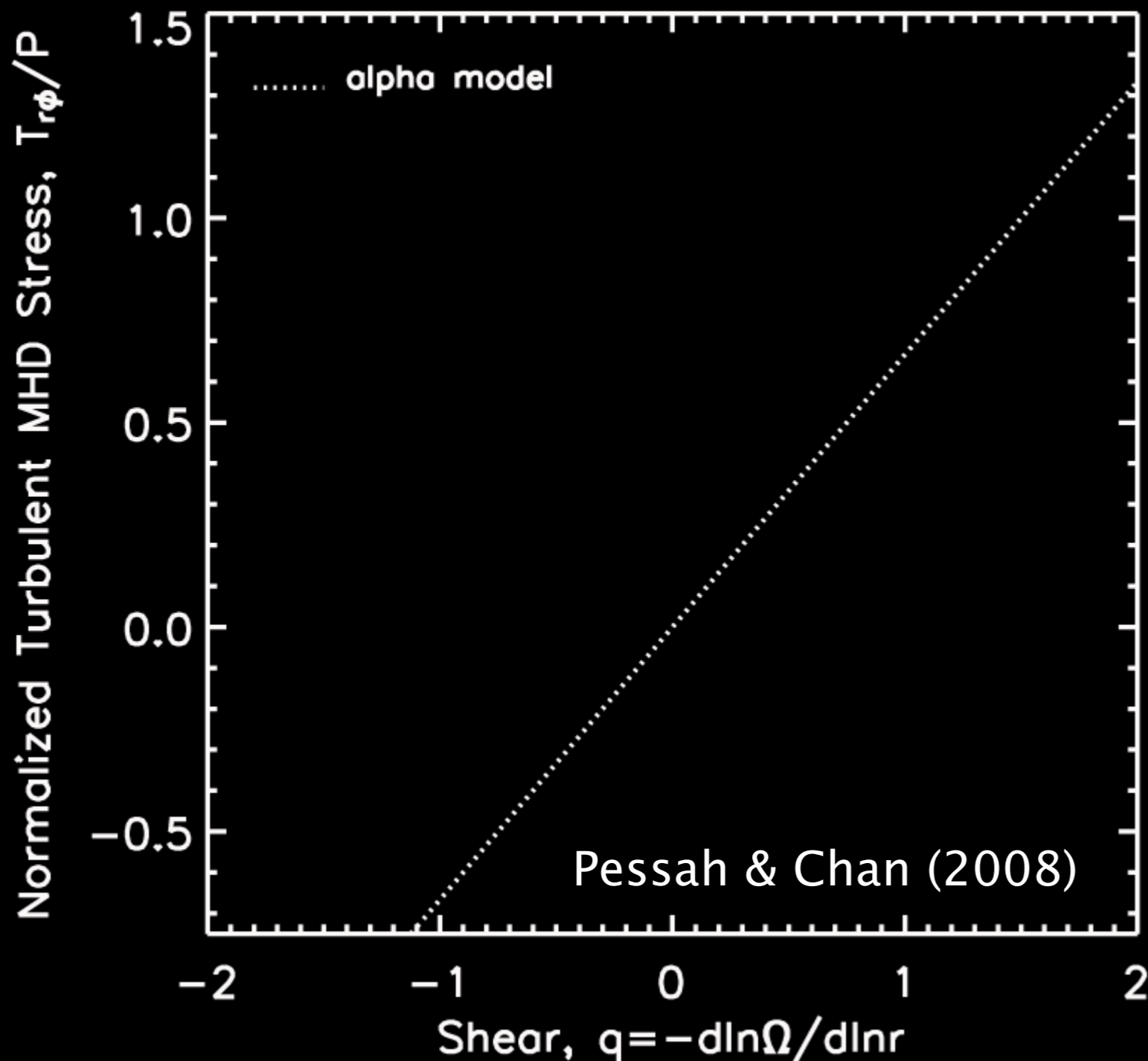
$$\dot{J} = \Omega R^2 \dot{M} - 2\pi R^2 H T_{r\phi} = \text{constant}$$

$$\dot{J} = \Omega R^2 \dot{M} + 2\pi R^2 \Sigma \nu R \Omega' = \text{constant}$$

“standard”

$$T_{r\phi} = -\nu (\Sigma/H) R \Omega'$$

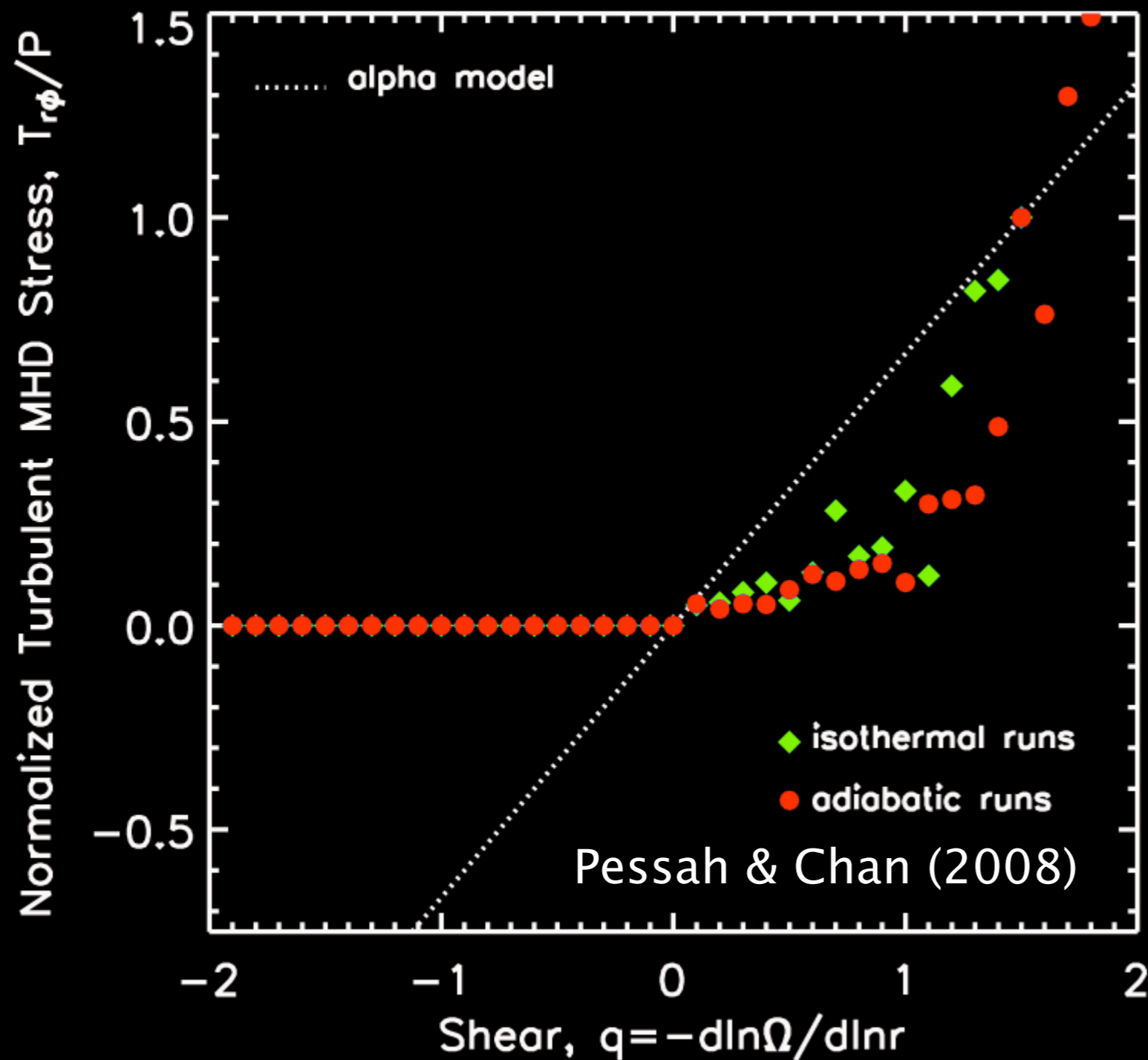
# MRI Turbulence $\neq$ $\alpha$ -Viscosity



“standard”

$$T_{r\phi} \sim -\frac{d \ln \Omega}{d \ln r}$$

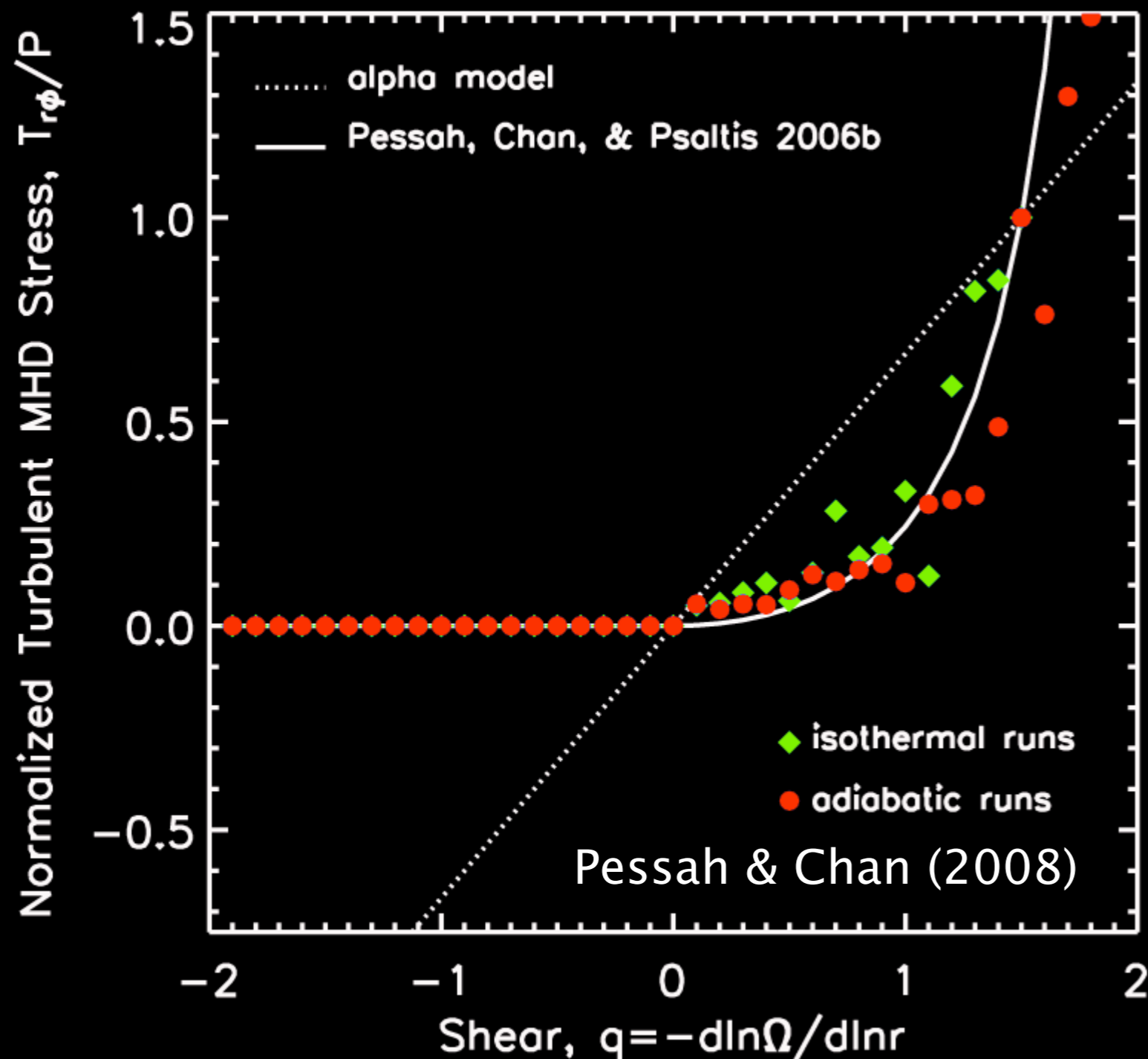
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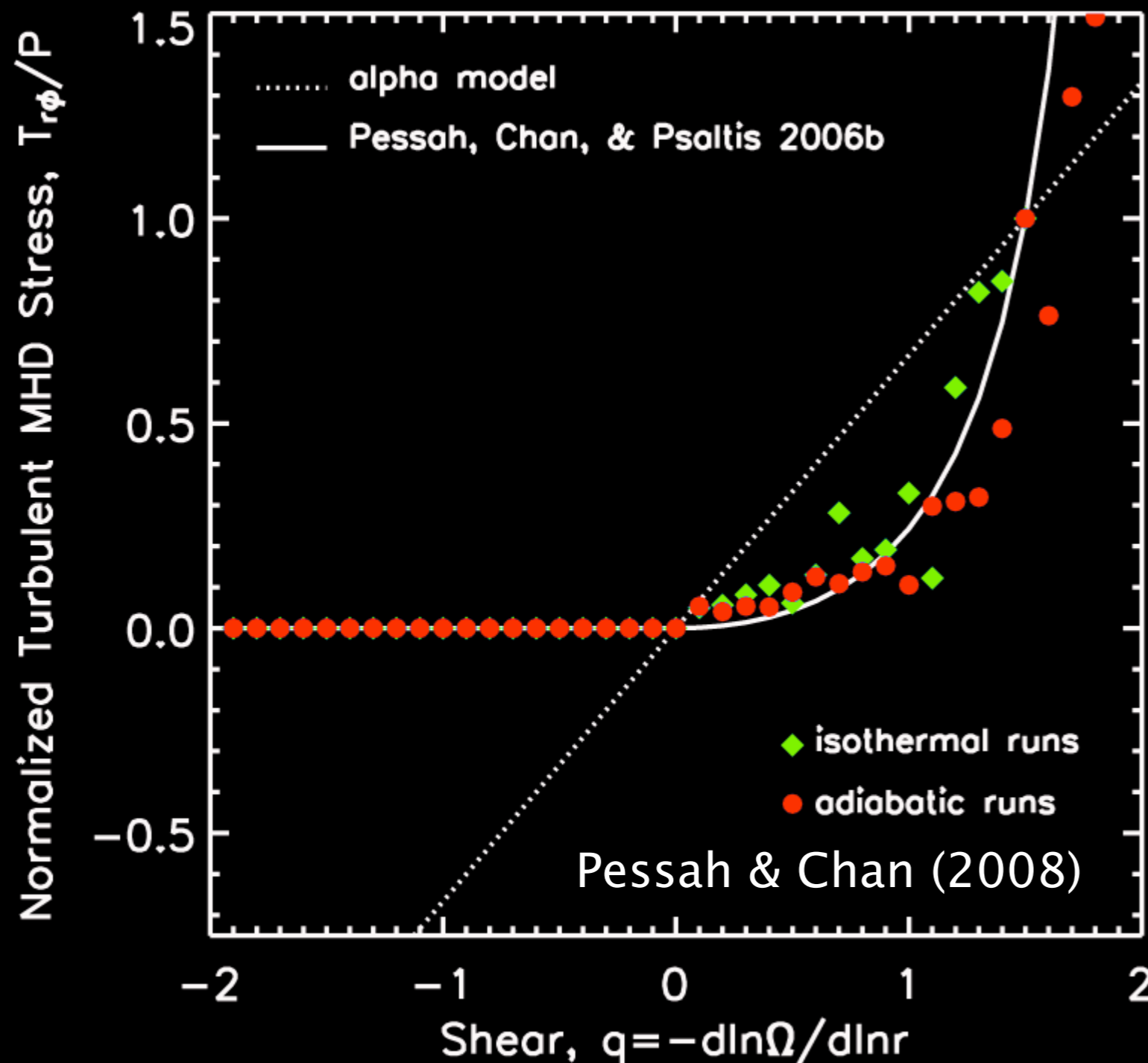
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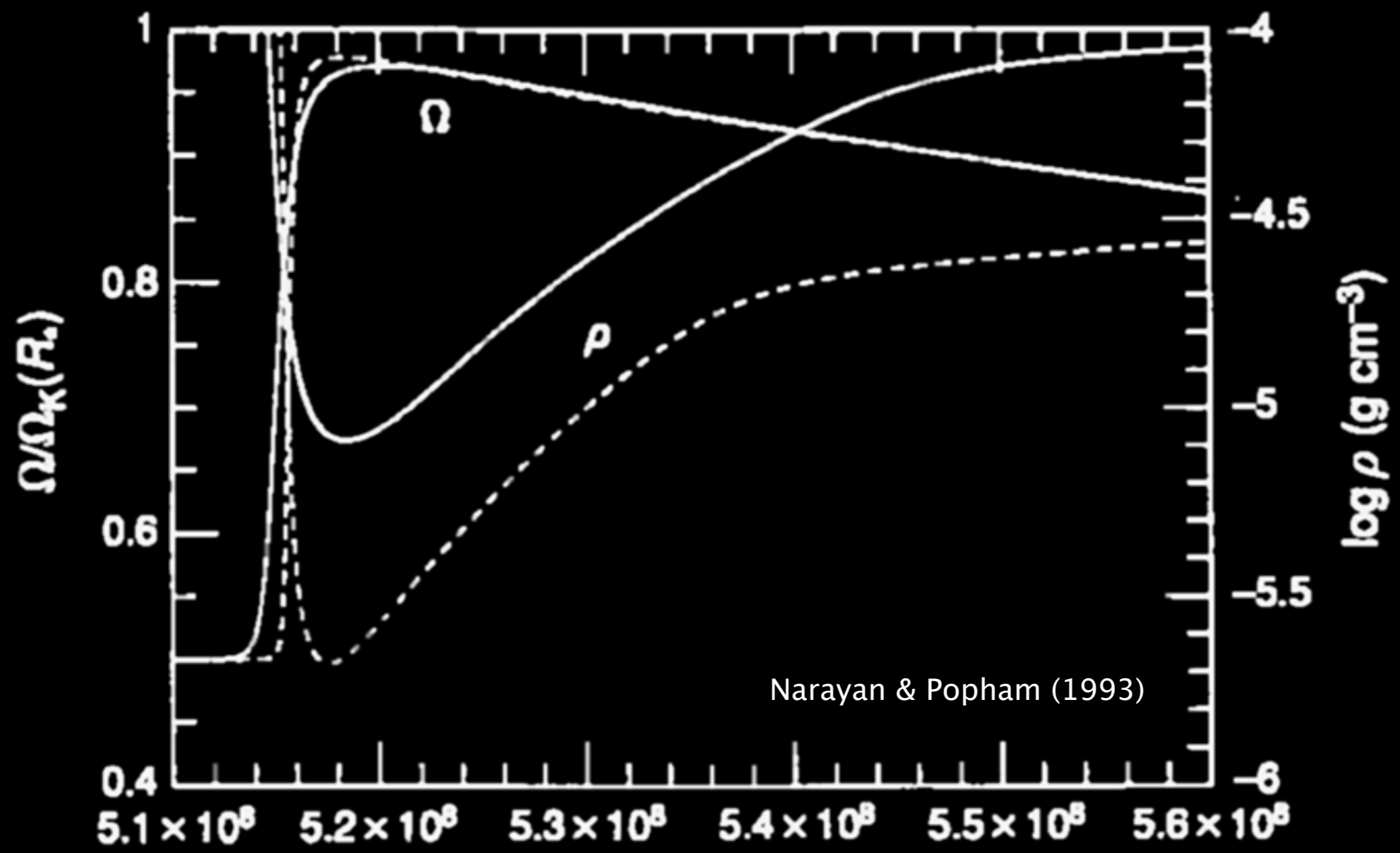


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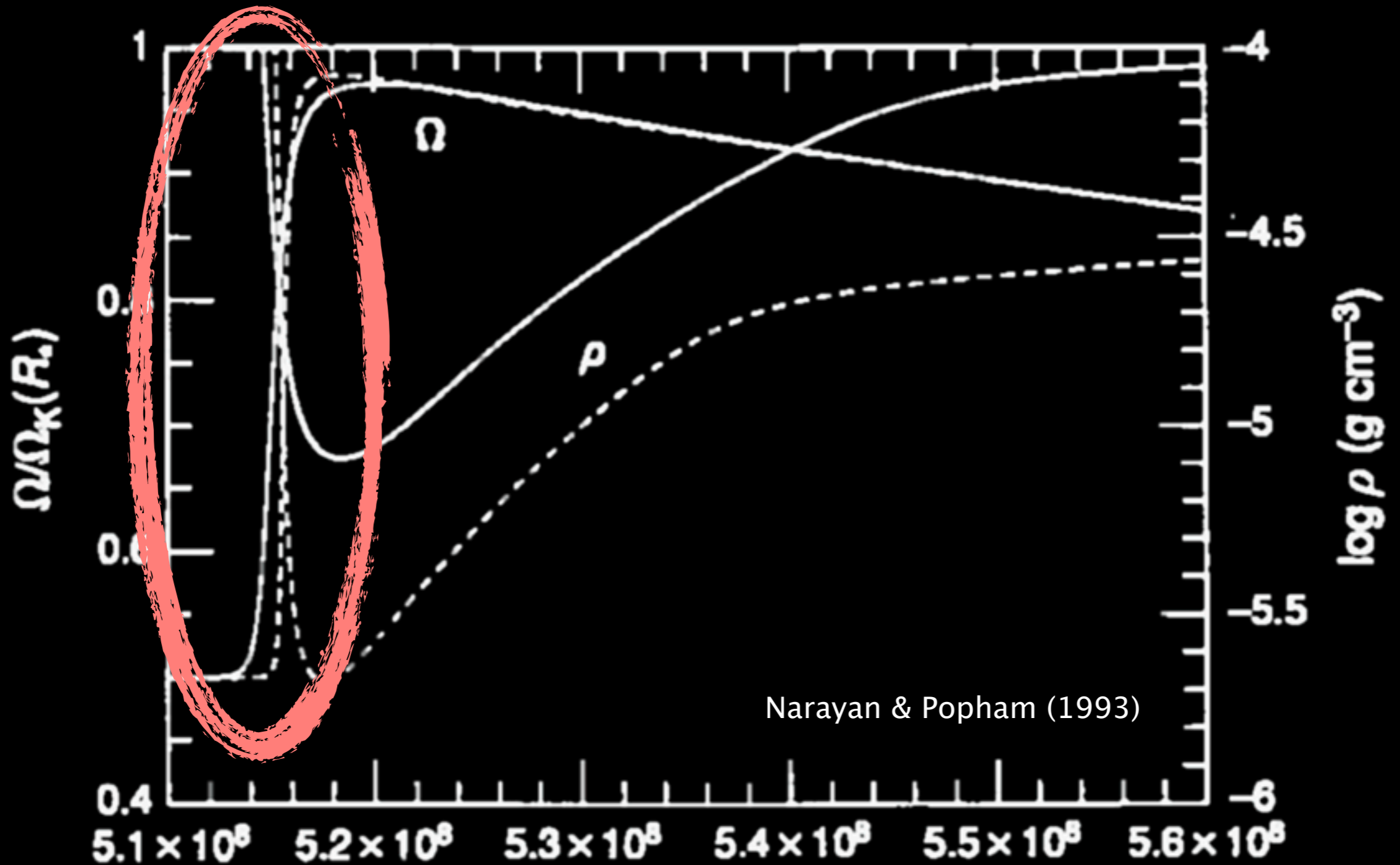
Angular momentum transport seems rather inefficient for negative  $q$  (beware of limited range explored!)

# What really happens here?



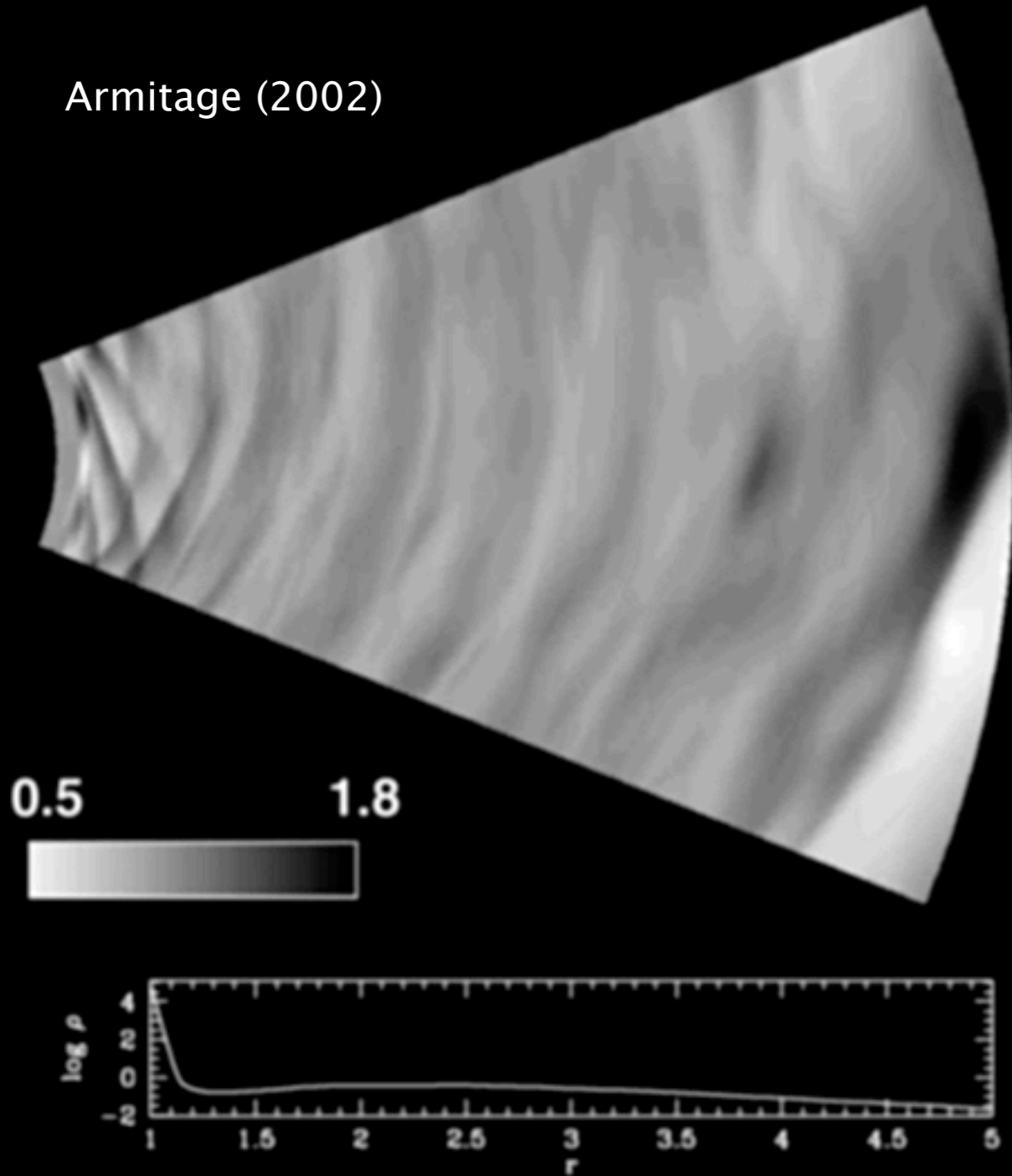


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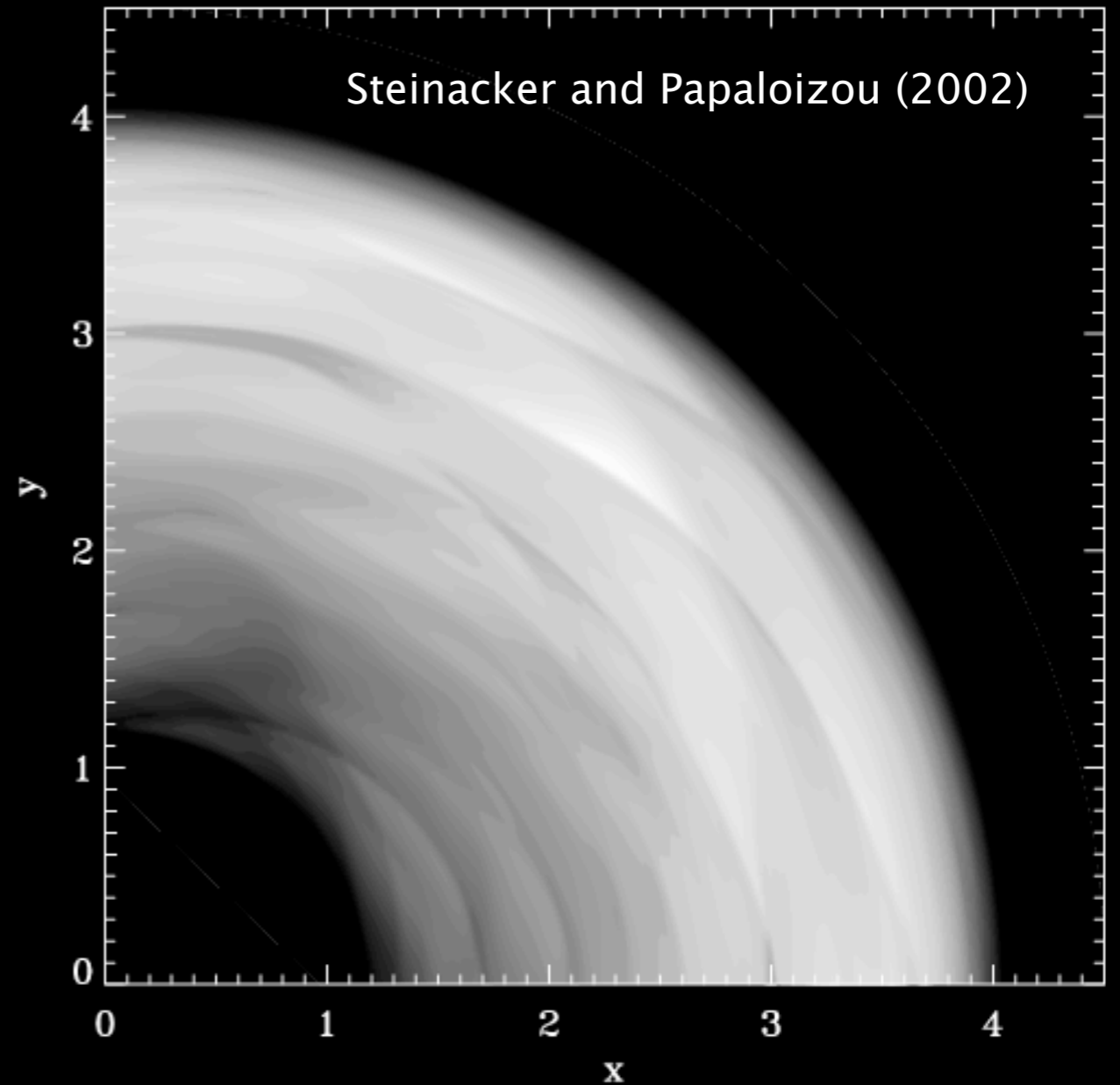


# Numerical Simulations I.

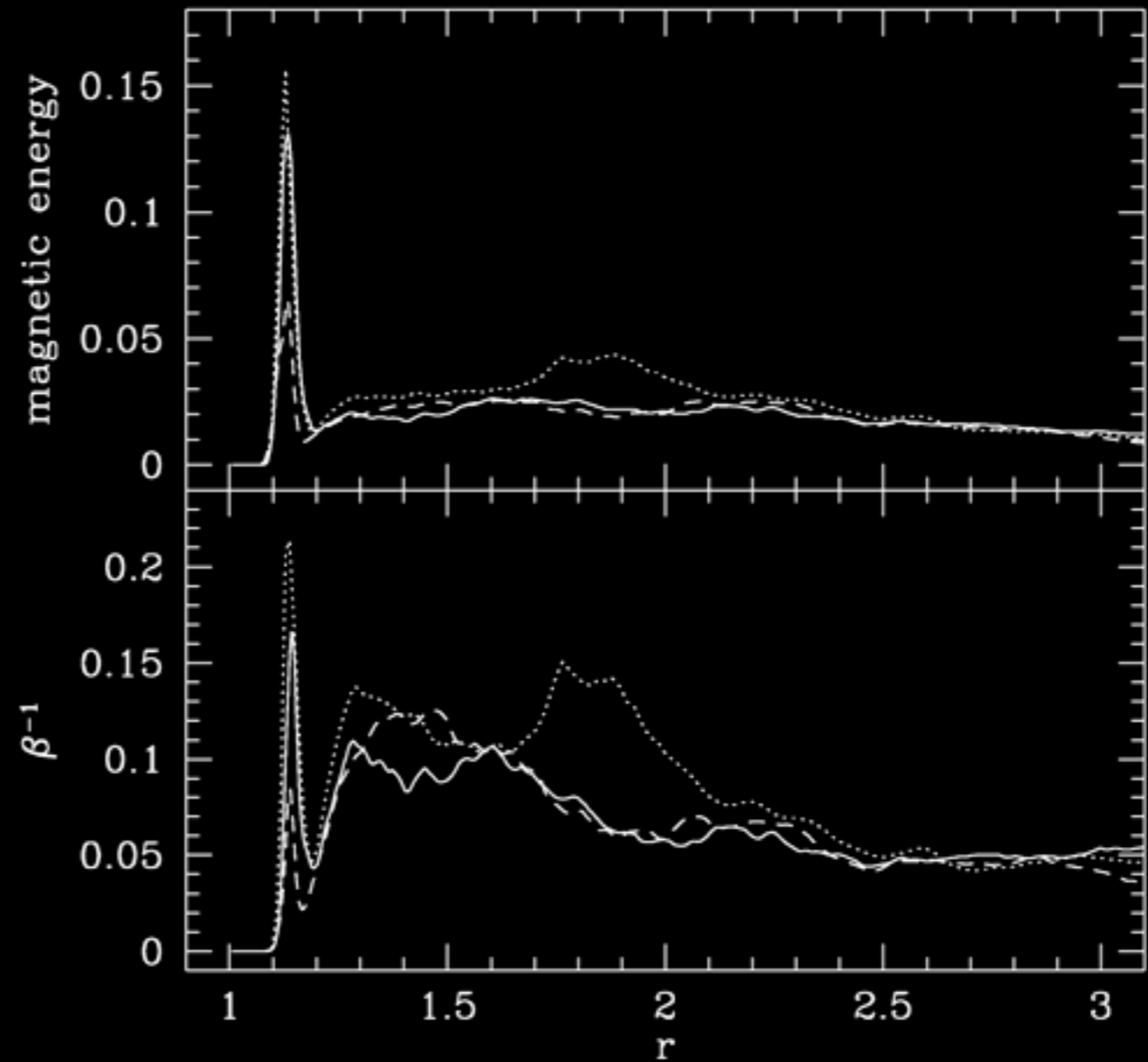
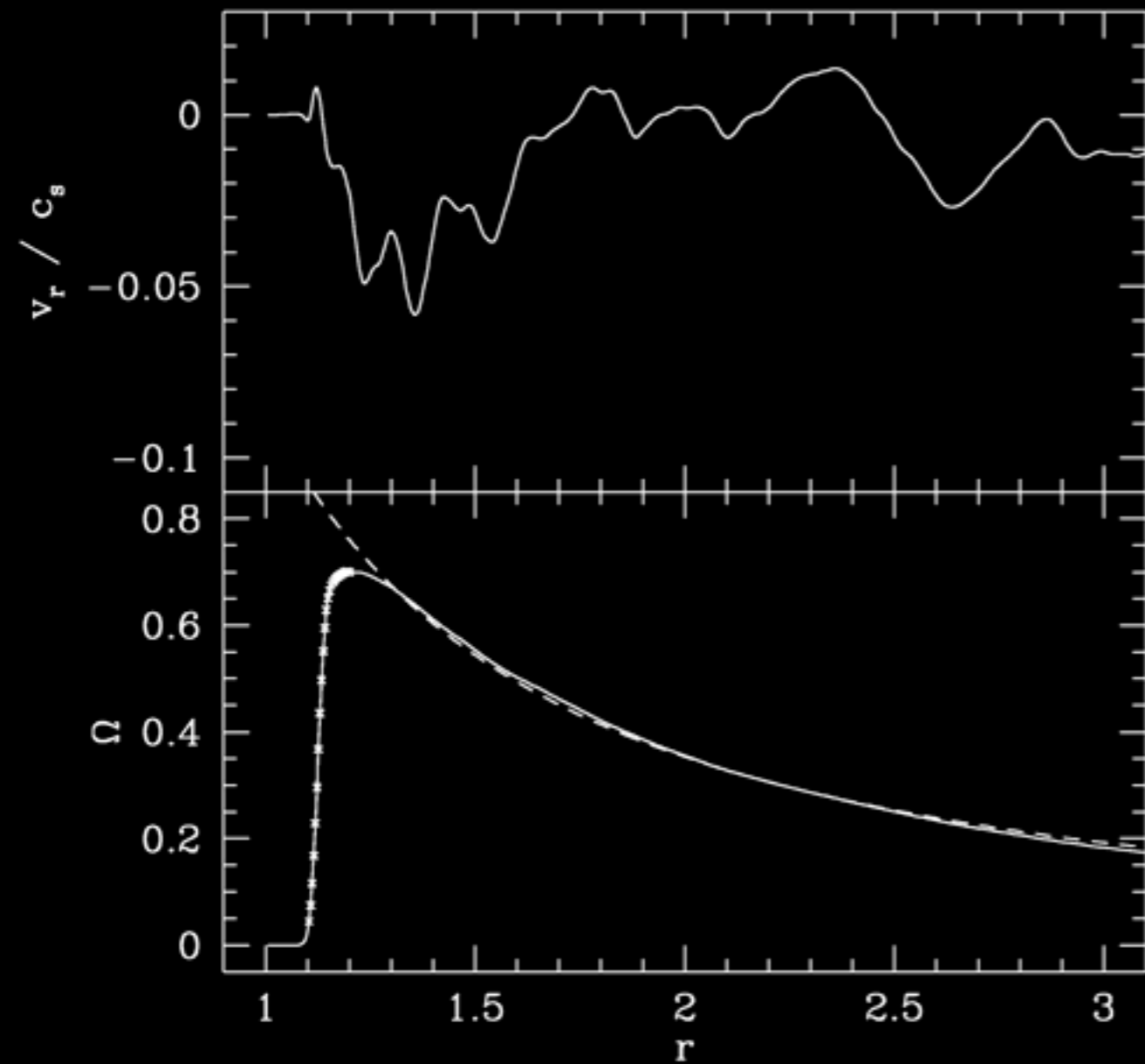
Armitage (2002)



Steinacker and Papaloizou (2002)

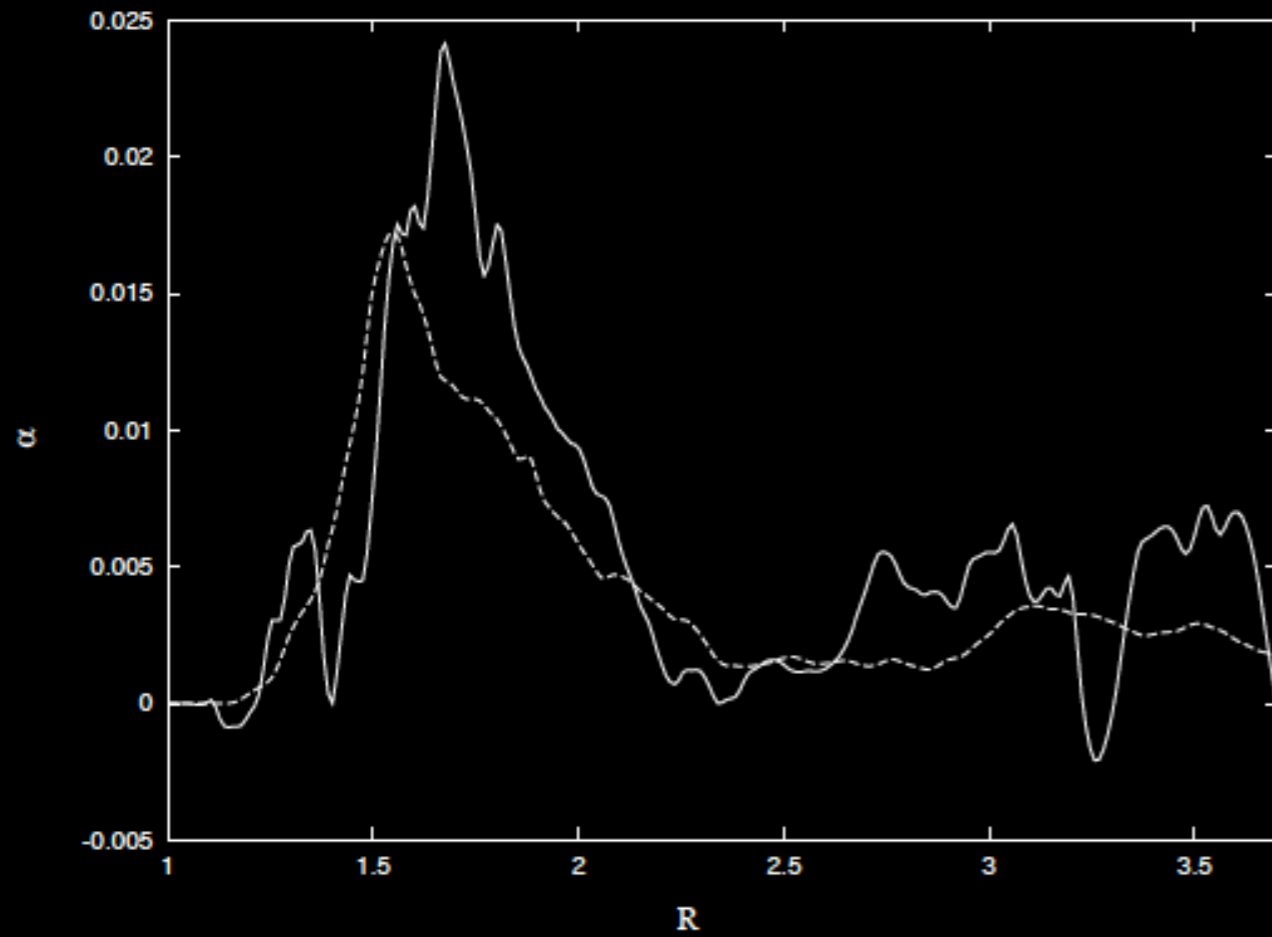


# Numerical Simulations II.



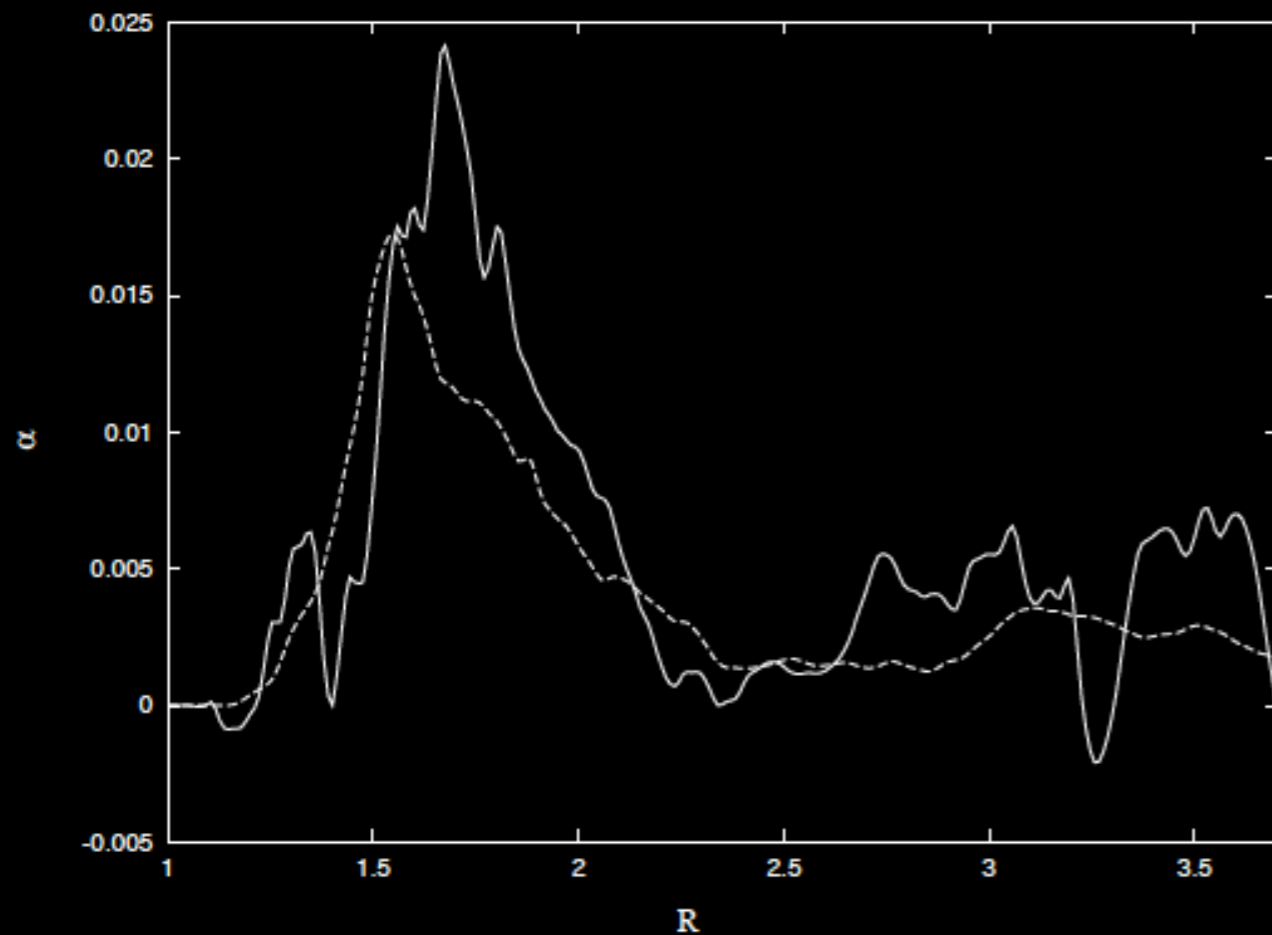
# Numerical Simulations III.

Steinacker and Papaloizou (2002)



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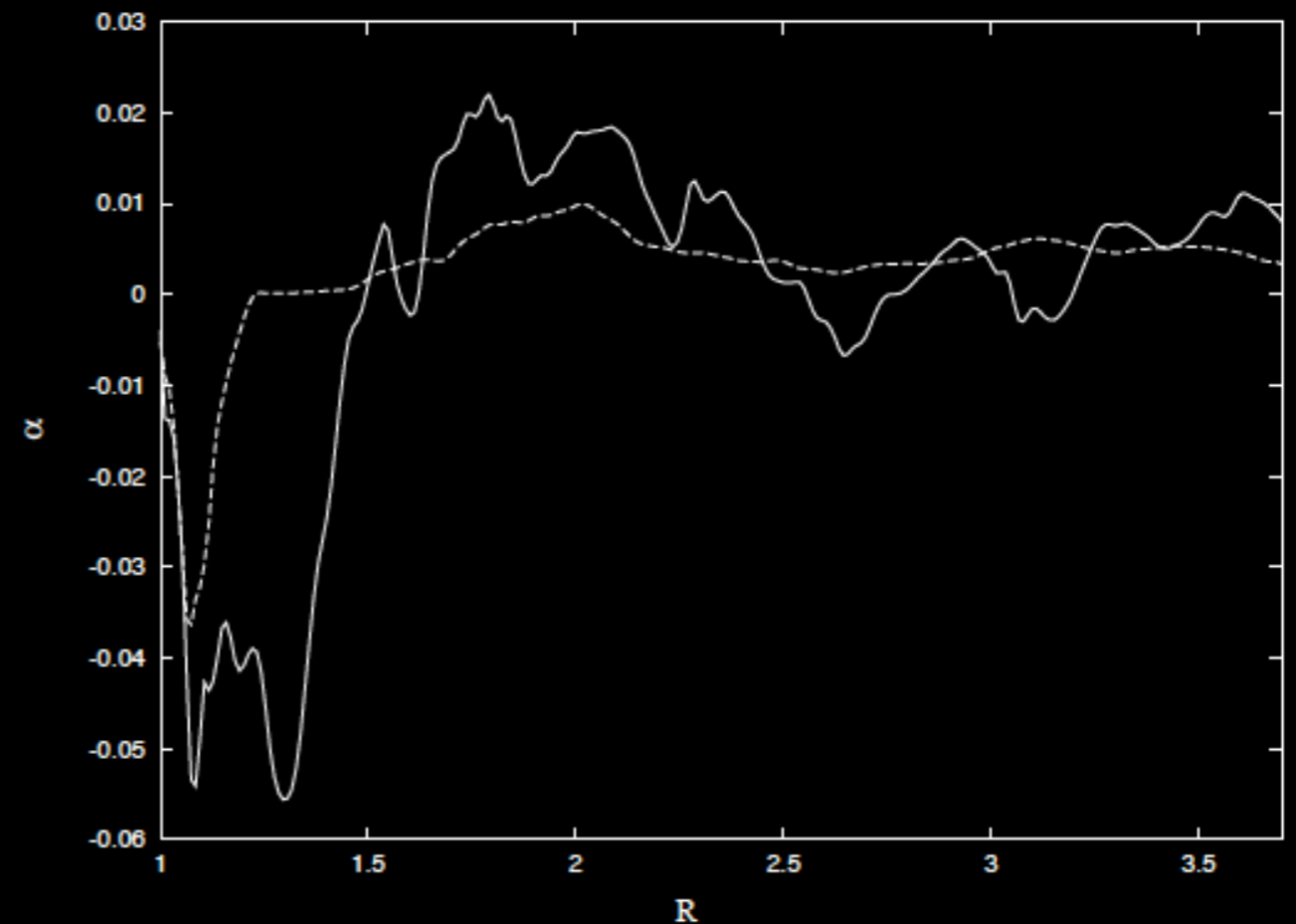
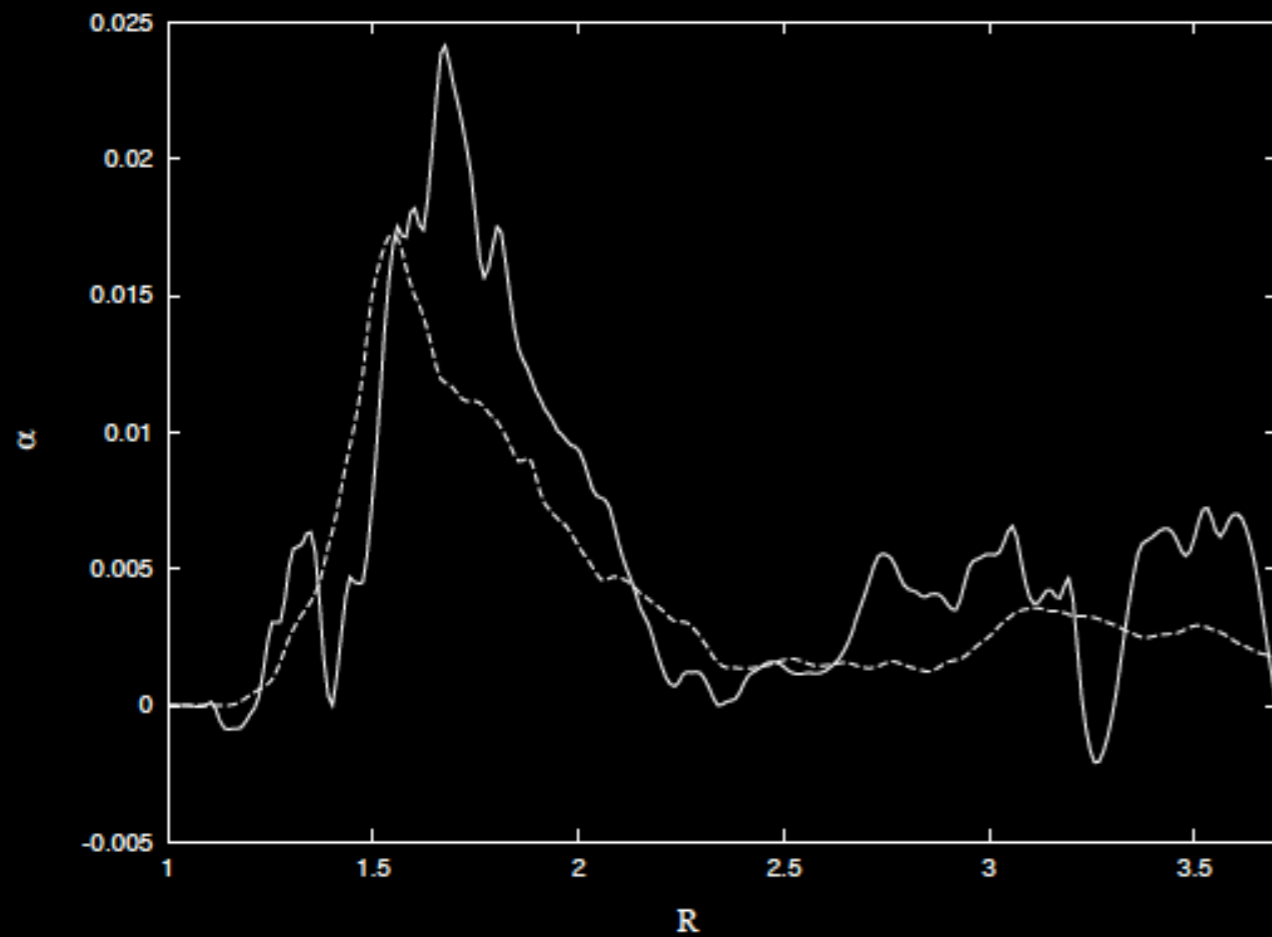
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We see lots of magnetic energy but not much magnetic/Maxwell stress in simulations (but...)

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# Some Insight from a Minimal Approach

---

- ✦ Standard incompressible shearing box approximation
- ✦ Consider a **single mode**  $\delta v_i, \delta b_i \sim e^{ik \cdot x}$   
(non-linear terms drop out, e.g., Goodman & Xu 1994)
- ✦ **Not just linearized** equations!
- ✦ Isolate **modes unrelated to MRI** ( $kz = 0$ ) [shear flow!!!]
- ✦ Explore the evolution of **energy** and **stress** as a function of the local **shear** parameter “q”

# Equations I.

---

- ✦ The momentum and induction equations

$$d_t \hat{\mathbf{u}} - q \Omega_0 \hat{u}_x \check{\mathbf{y}} = i\omega_A \hat{\mathbf{b}} - \nu k^2 \hat{\mathbf{u}} - 2\Omega_0 \check{\mathbf{z}} \times \hat{\mathbf{u}} - ik\hat{P},$$

$$d_t \hat{\mathbf{b}} + q \Omega_0 \hat{b}_x \check{\mathbf{y}} = i\omega_A \hat{\mathbf{u}} - \eta k^2 \hat{\mathbf{b}}.$$

- ✦ Note that  $\omega_A \equiv \mathbf{B}(t) \cdot \mathbf{k}(t) = \text{constant}$

because  $\partial_t \mathbf{B}_0 = -q \Omega_0 B_{0x} \check{\mathbf{y}}$

$$\mathbf{k}' \cdot \mathbf{x}' = \mathbf{k}(t) \cdot \mathbf{x} = (k'_x + q \Omega_0 t k'_y) x + k'_y y$$



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# Equations II.

---

- ✦ Define dimensionless quantities

$$\tau \equiv k_x(t)/k_y = q \Omega_0 t \quad \omega \equiv \omega_A / q \Omega_0$$

- ✦ The system of equations reduces to

$$\frac{d}{d\tau} \begin{bmatrix} \hat{u}_x \\ \hat{b}_x \end{bmatrix} = \begin{bmatrix} -\Gamma(\tau) & i\omega \\ i\omega & 0 \end{bmatrix} \begin{bmatrix} \hat{u}_x \\ \hat{b}_x \end{bmatrix}$$

$$\Gamma(\tau) \equiv 2\tau / (\tau^2 + 1)$$

# Results

---

- ✦ Reduce the coupled equations to one **2nd order ODE**

$$\frac{d^2}{d\tau^2} \hat{b}_x + \Gamma(\tau) \frac{d}{d\tau} \hat{b}_x + \omega^2 \hat{b}_x = 0$$

- ✦ For  $\tau^2 \gg 1$ , we get a spherical **Bessel equation**

$$\hat{u}_x = S j_1(\omega\tau) + C y_1(\omega\tau)$$

$$\hat{b}_x = -iS j_0(\omega\tau) - iC y_0(\omega\tau)$$

$$\hat{u}_y = -\tau \hat{u}_x$$

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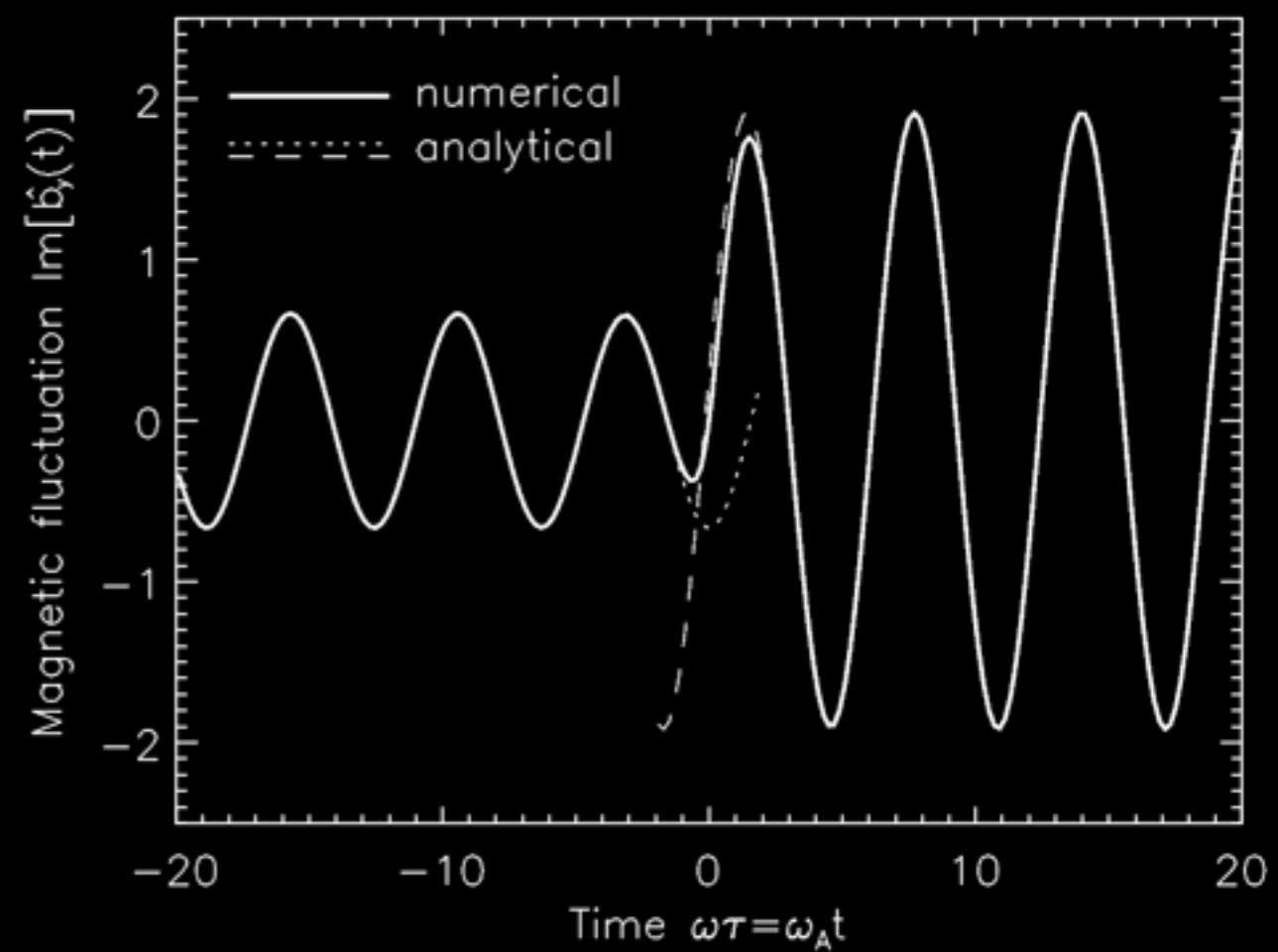
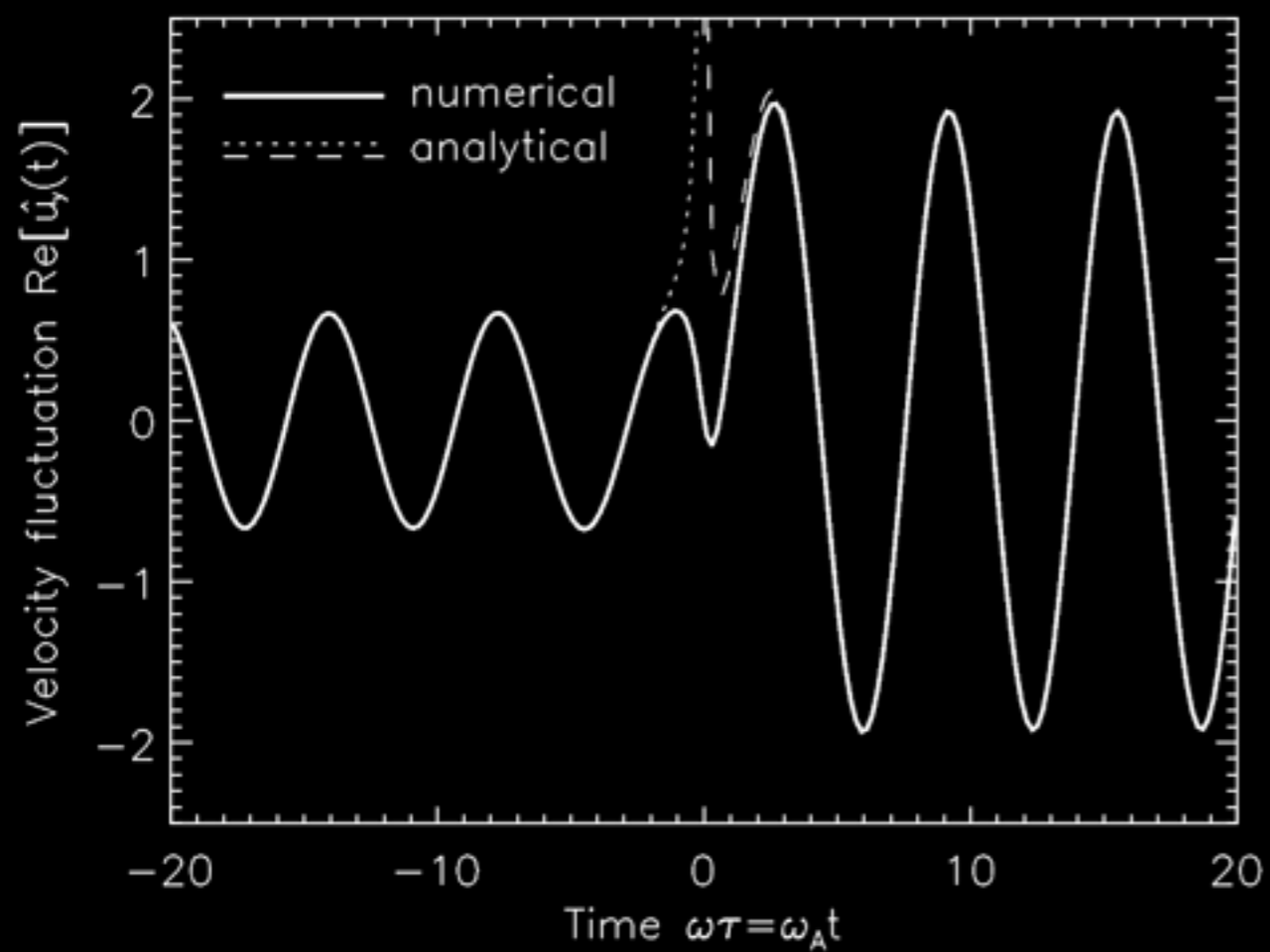
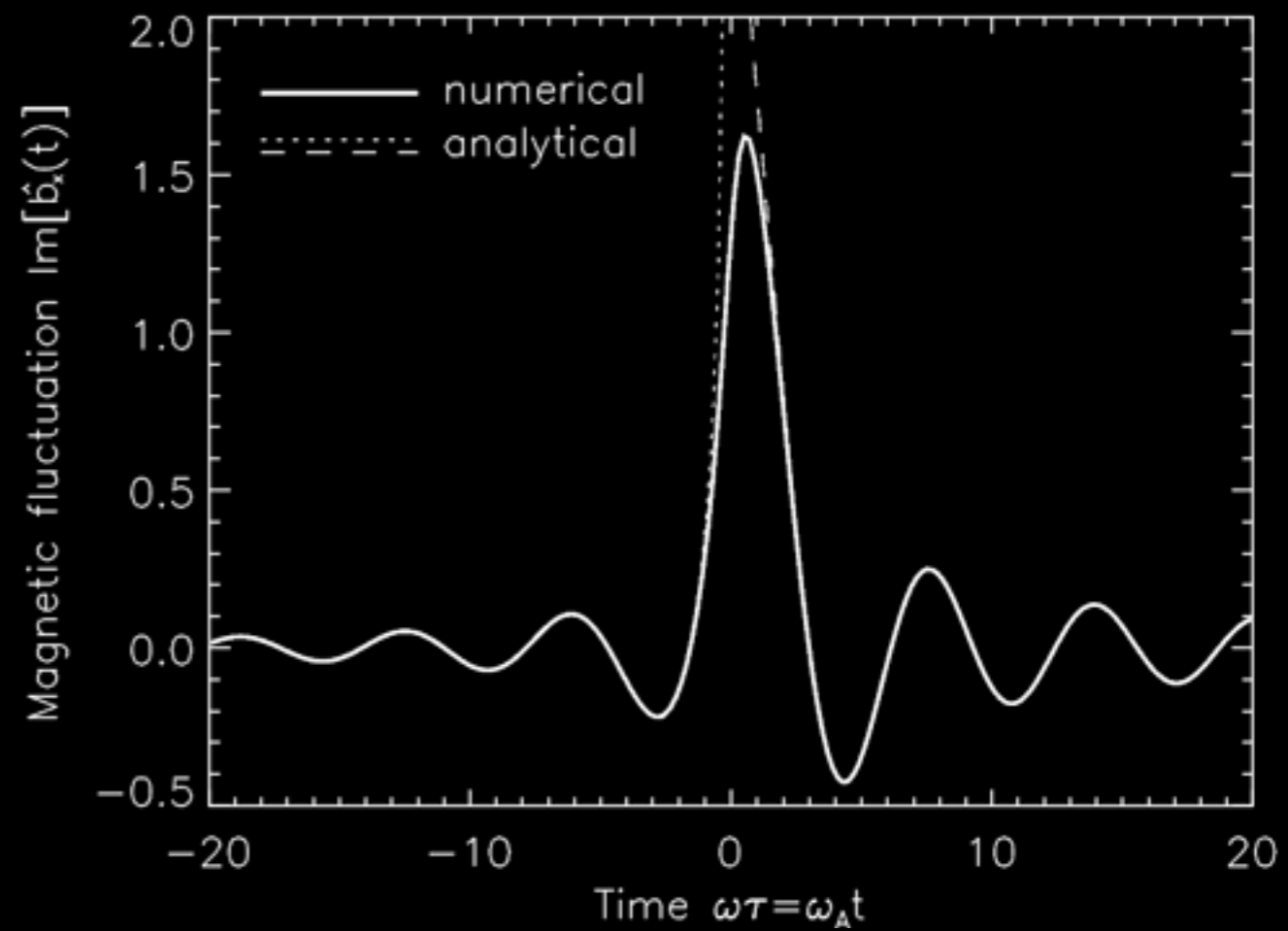
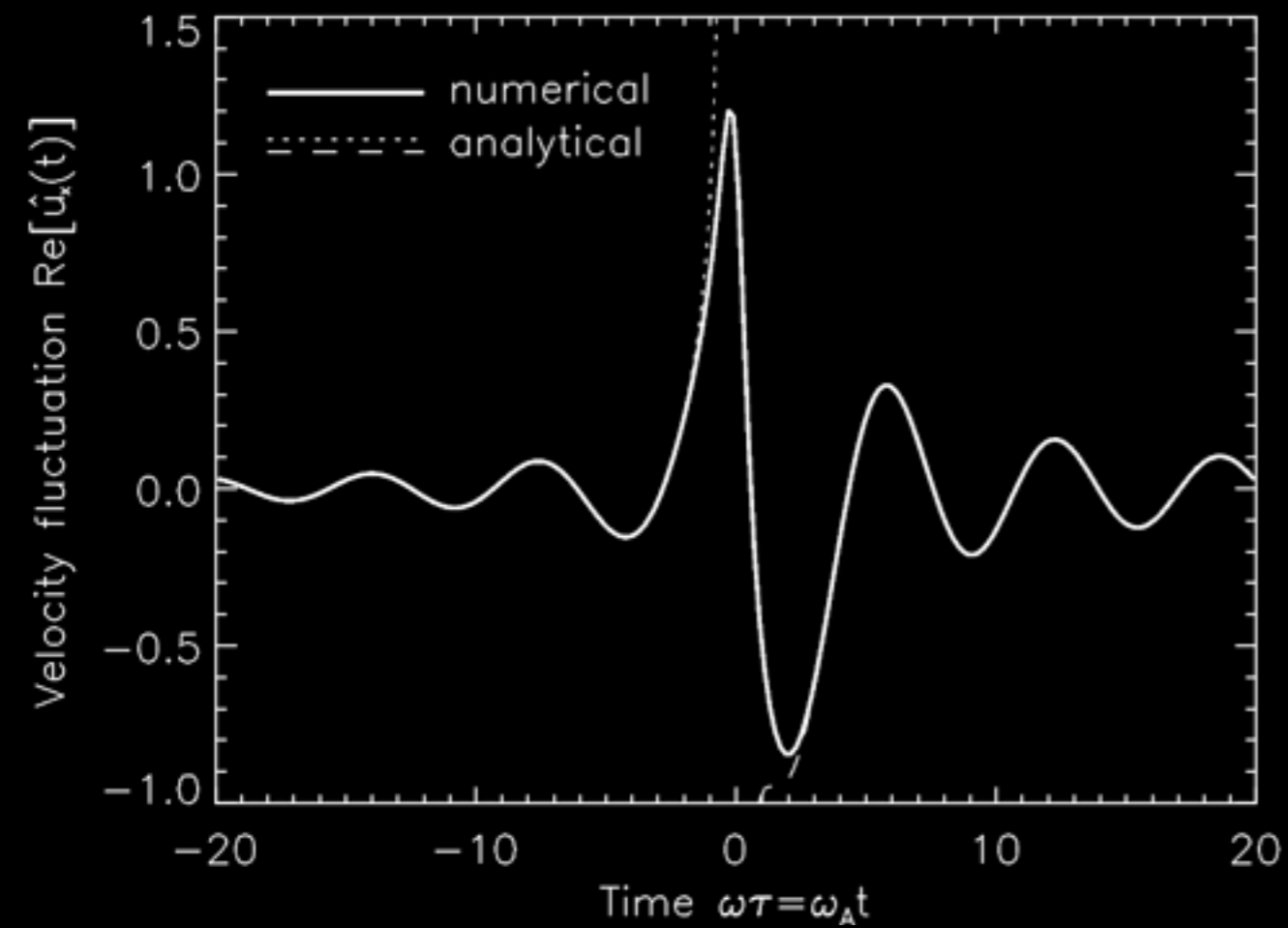
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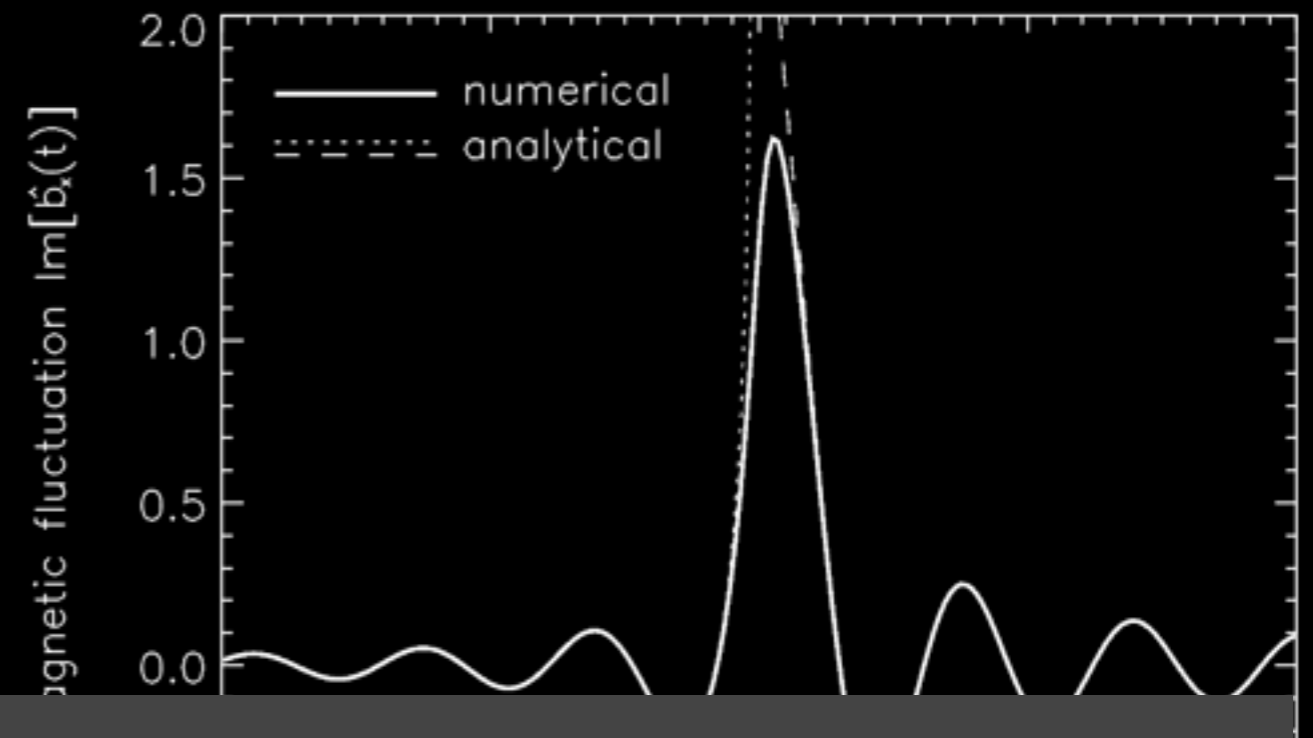
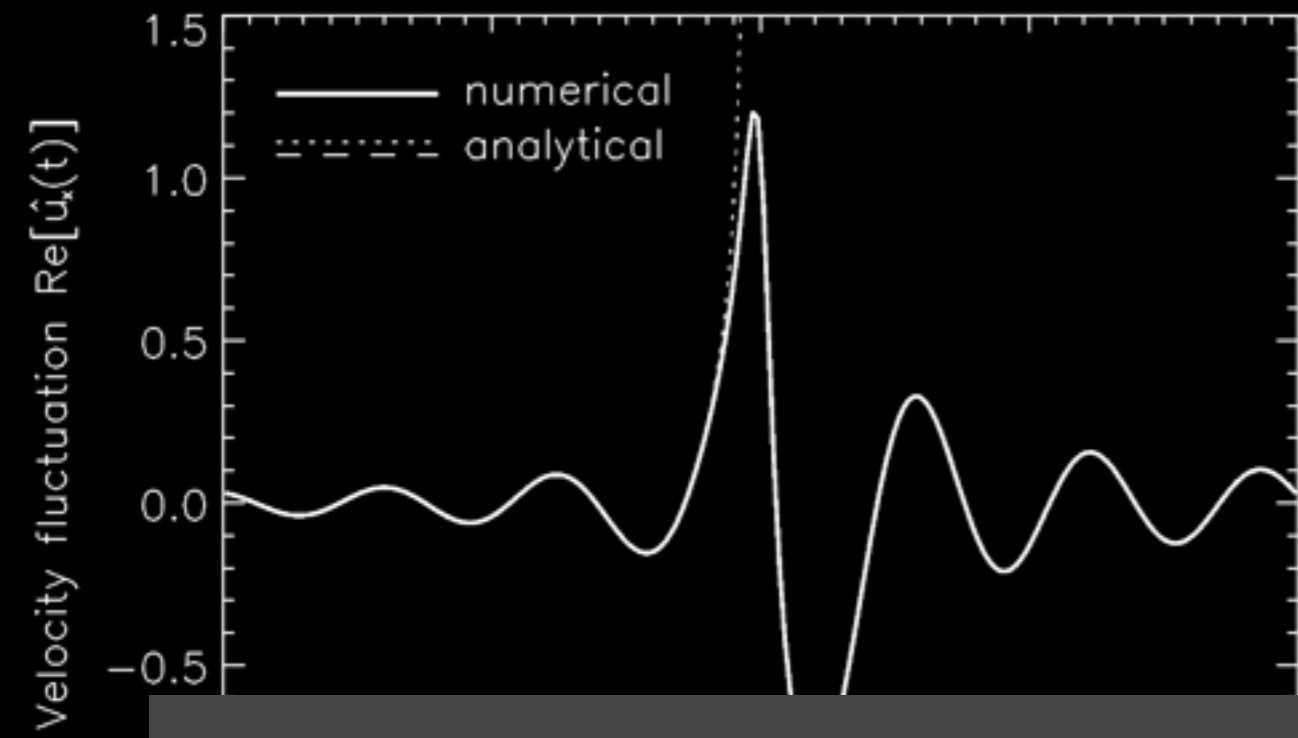
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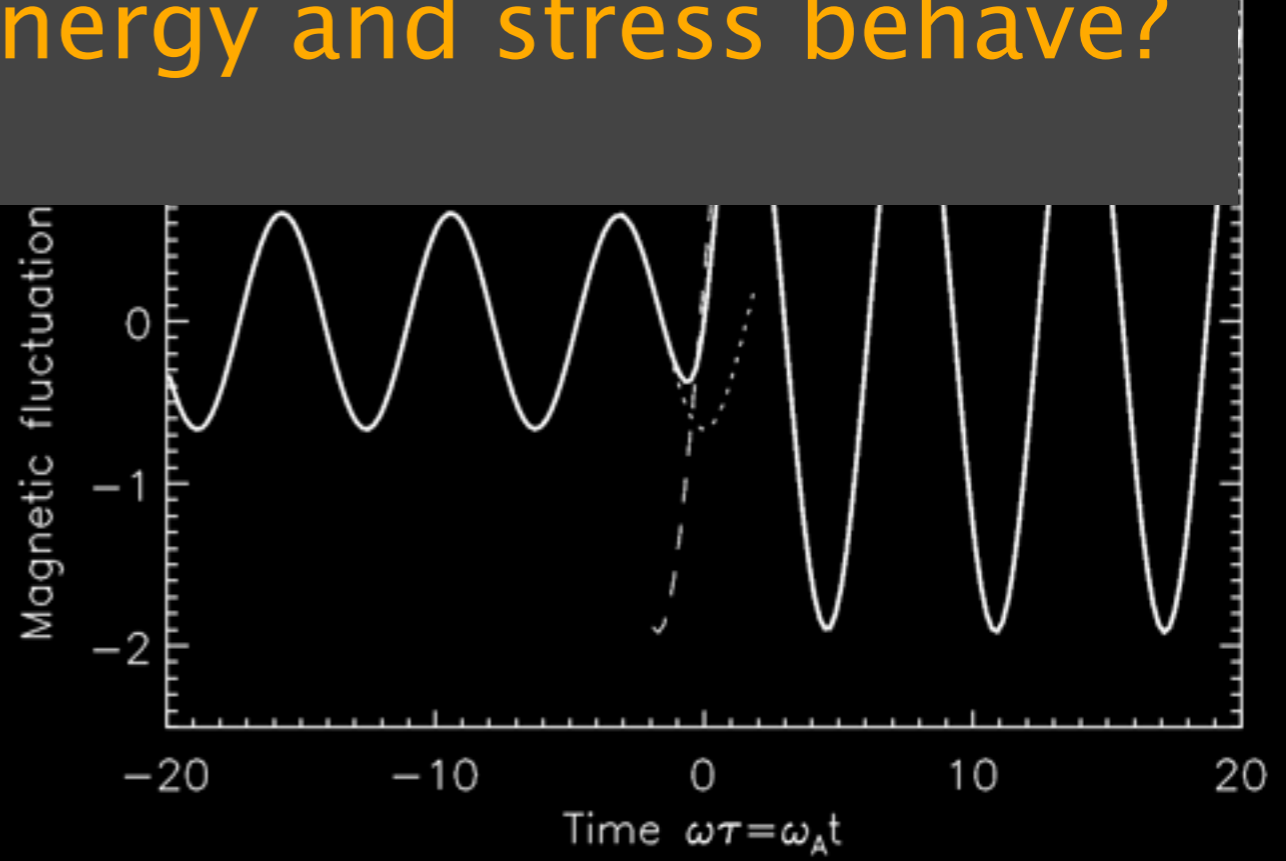
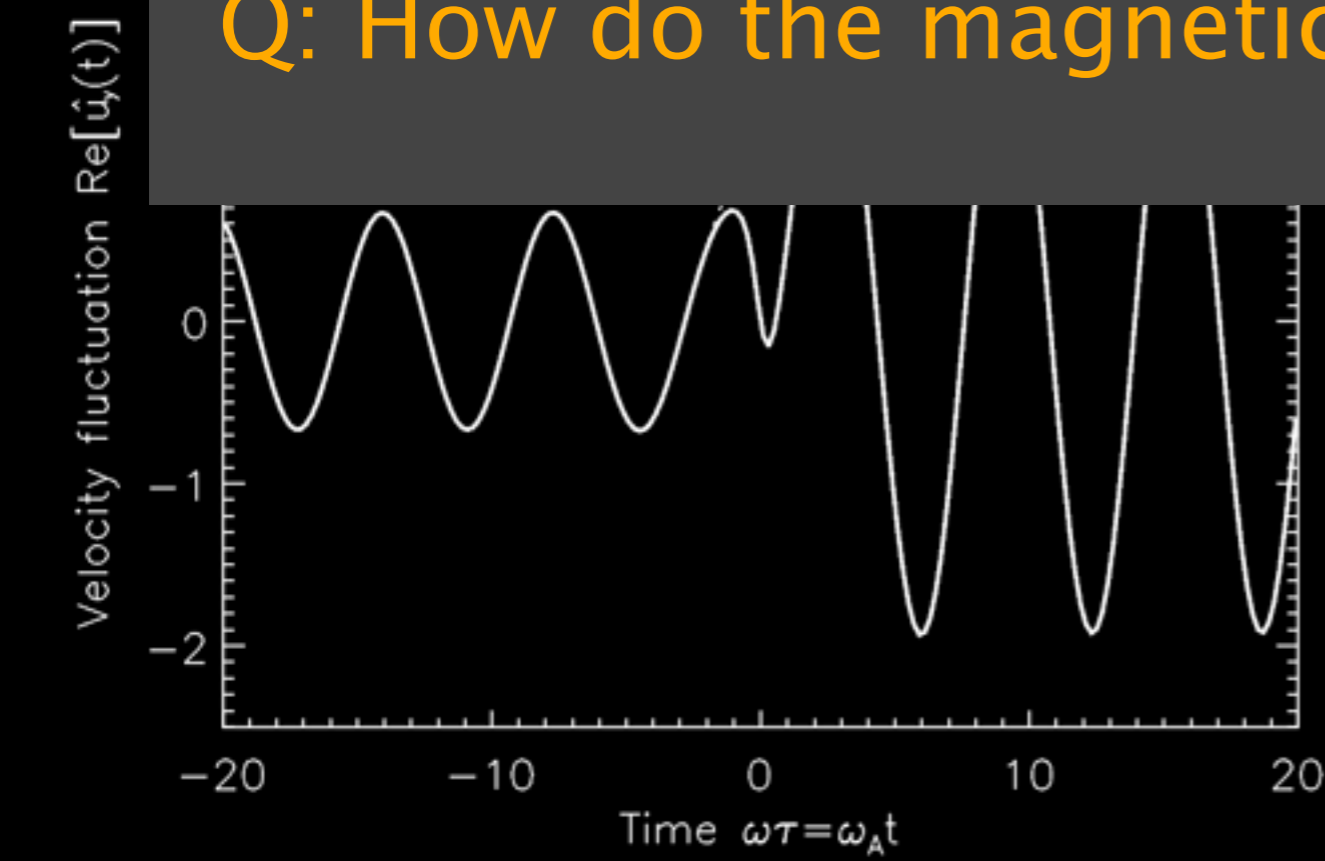
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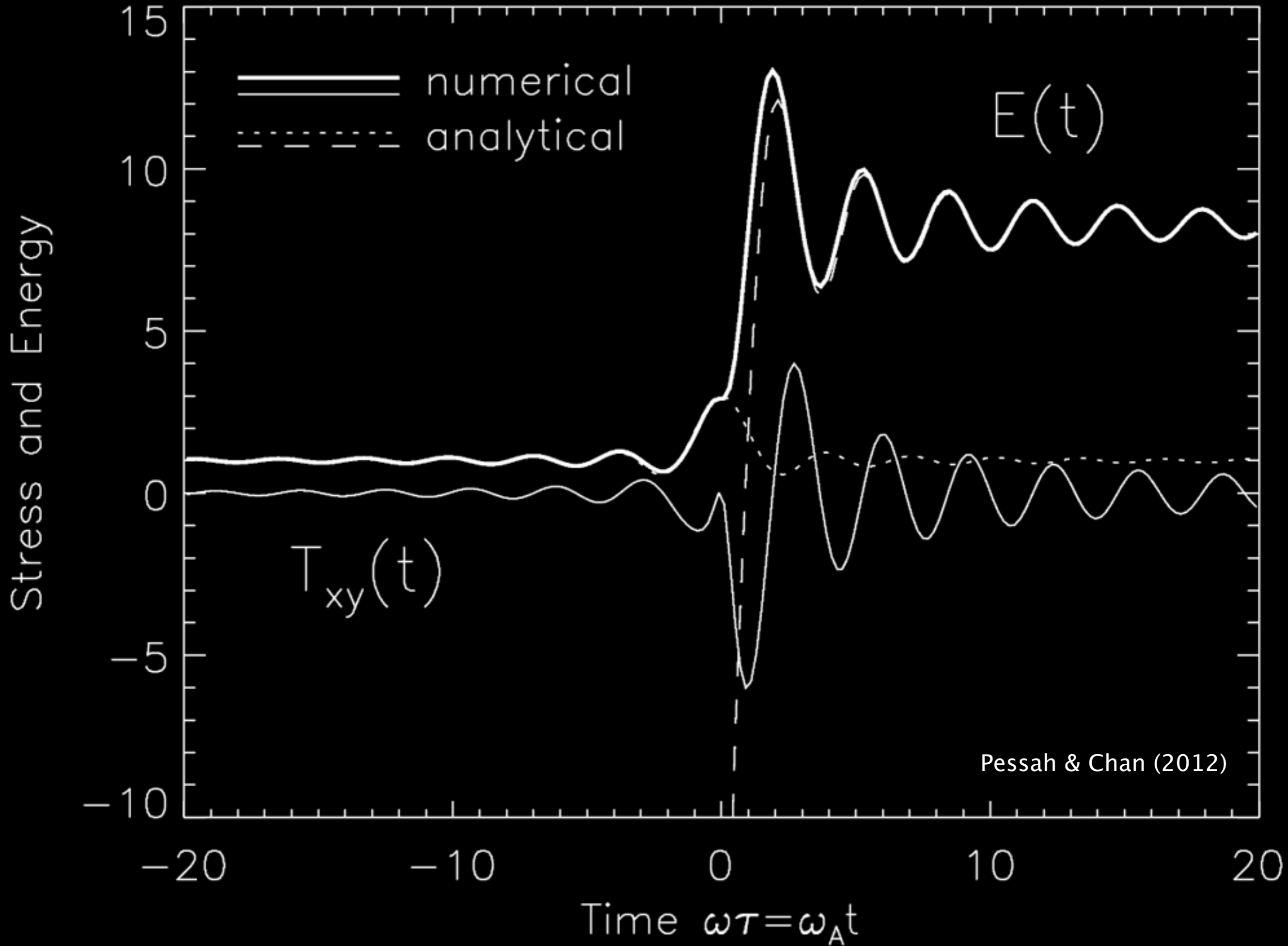




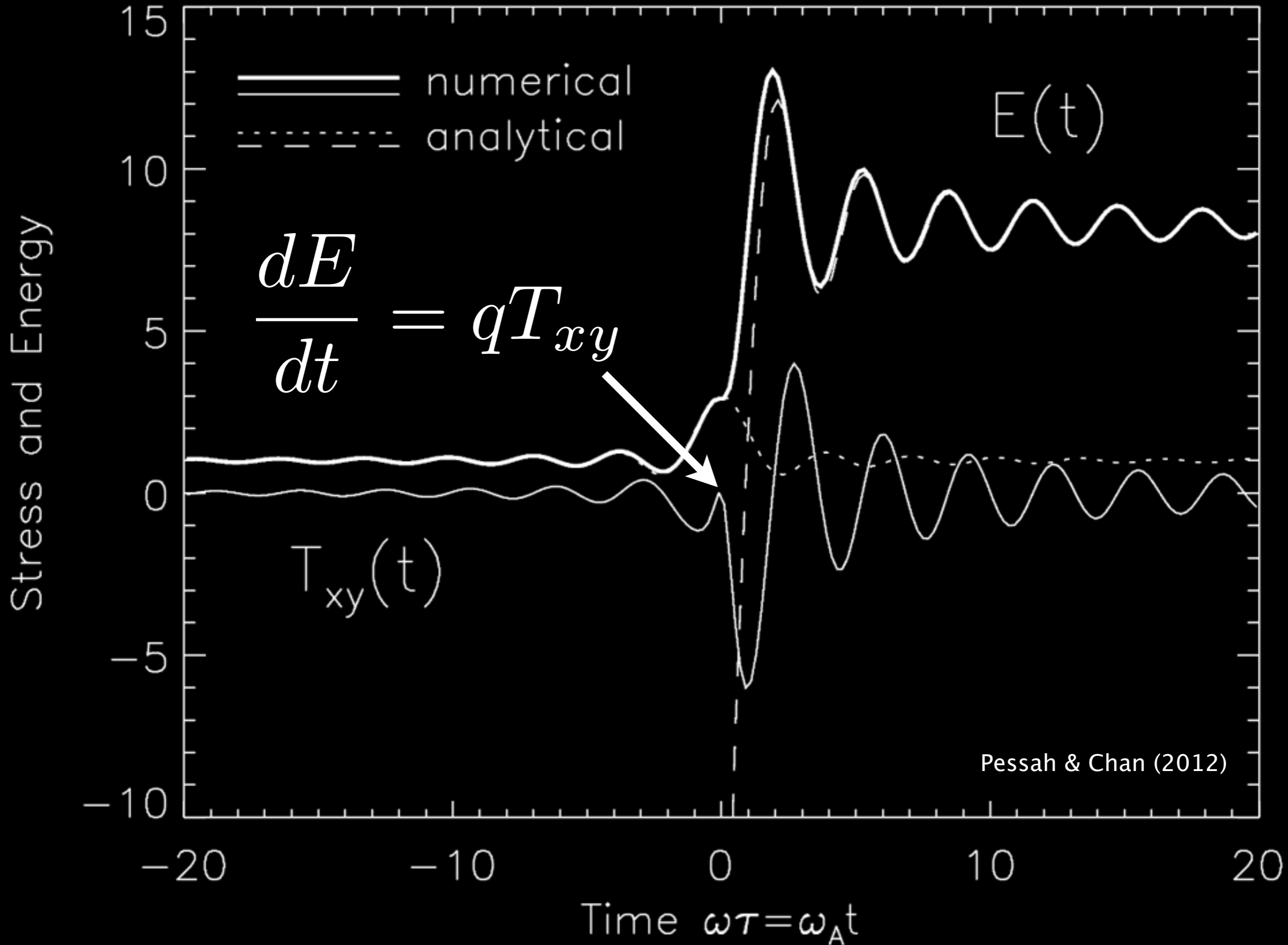
Similar results than in Balbus & Hawley 1992...

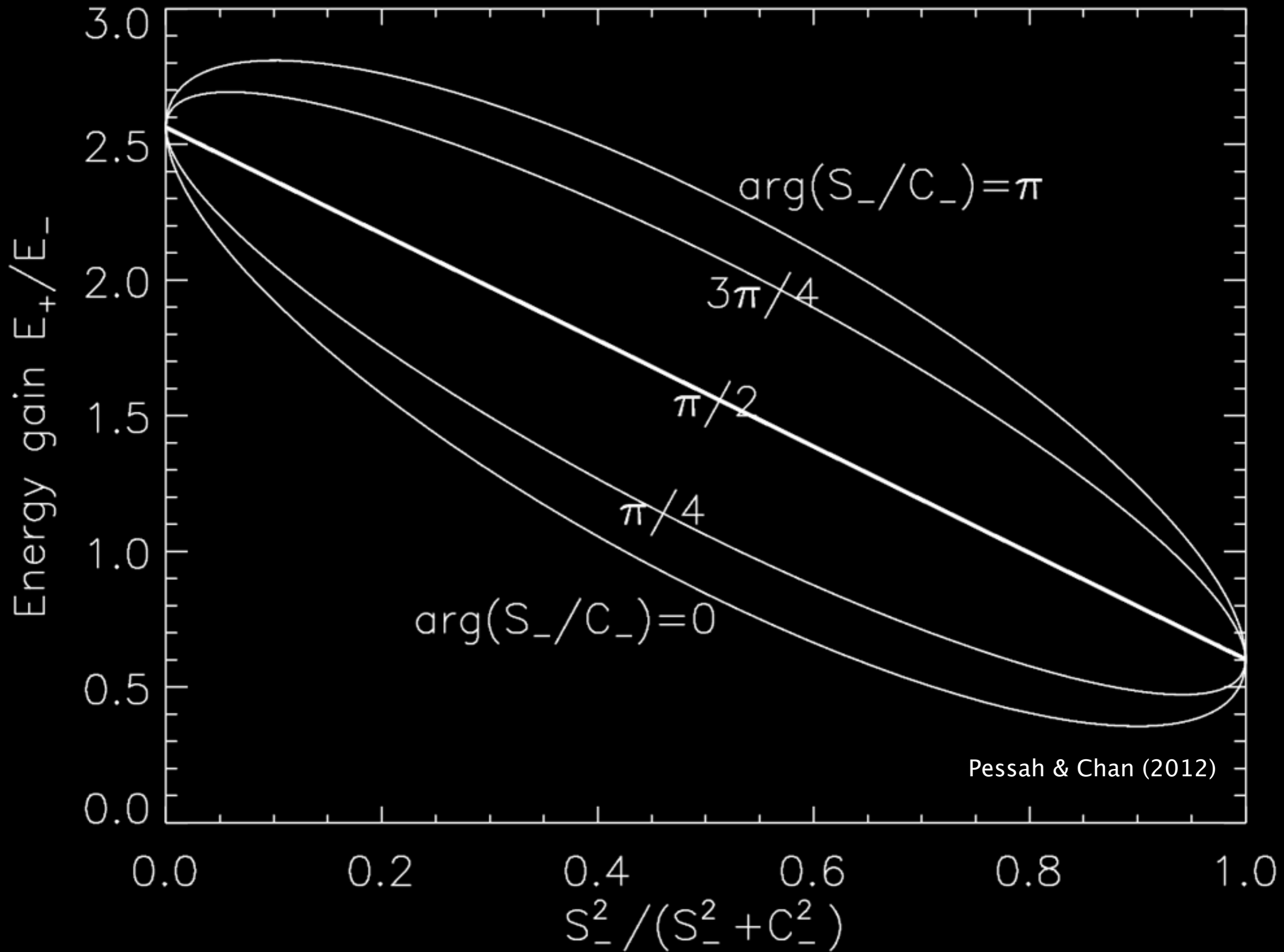
Q: How do the magnetic energy and stress behave?



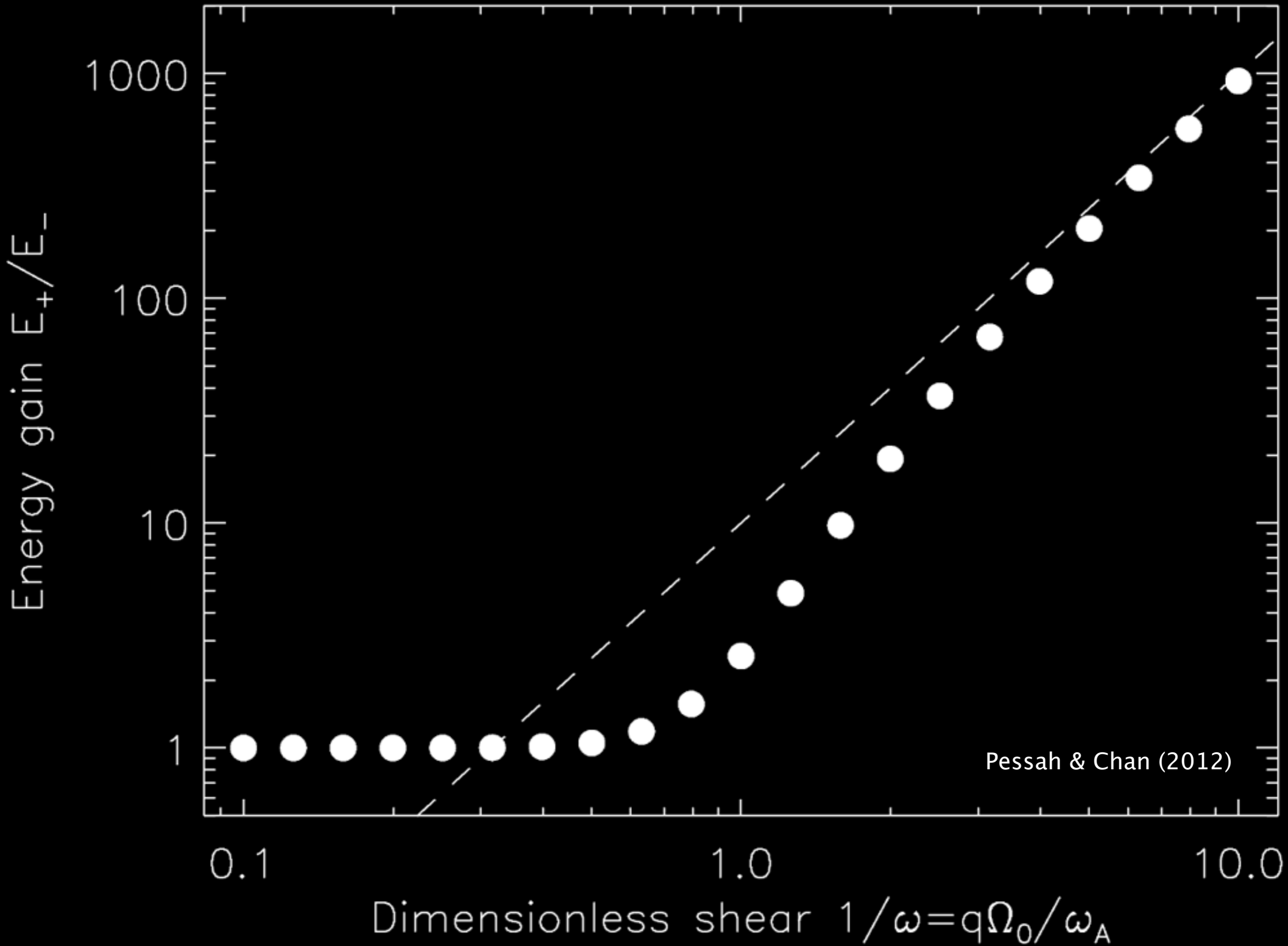


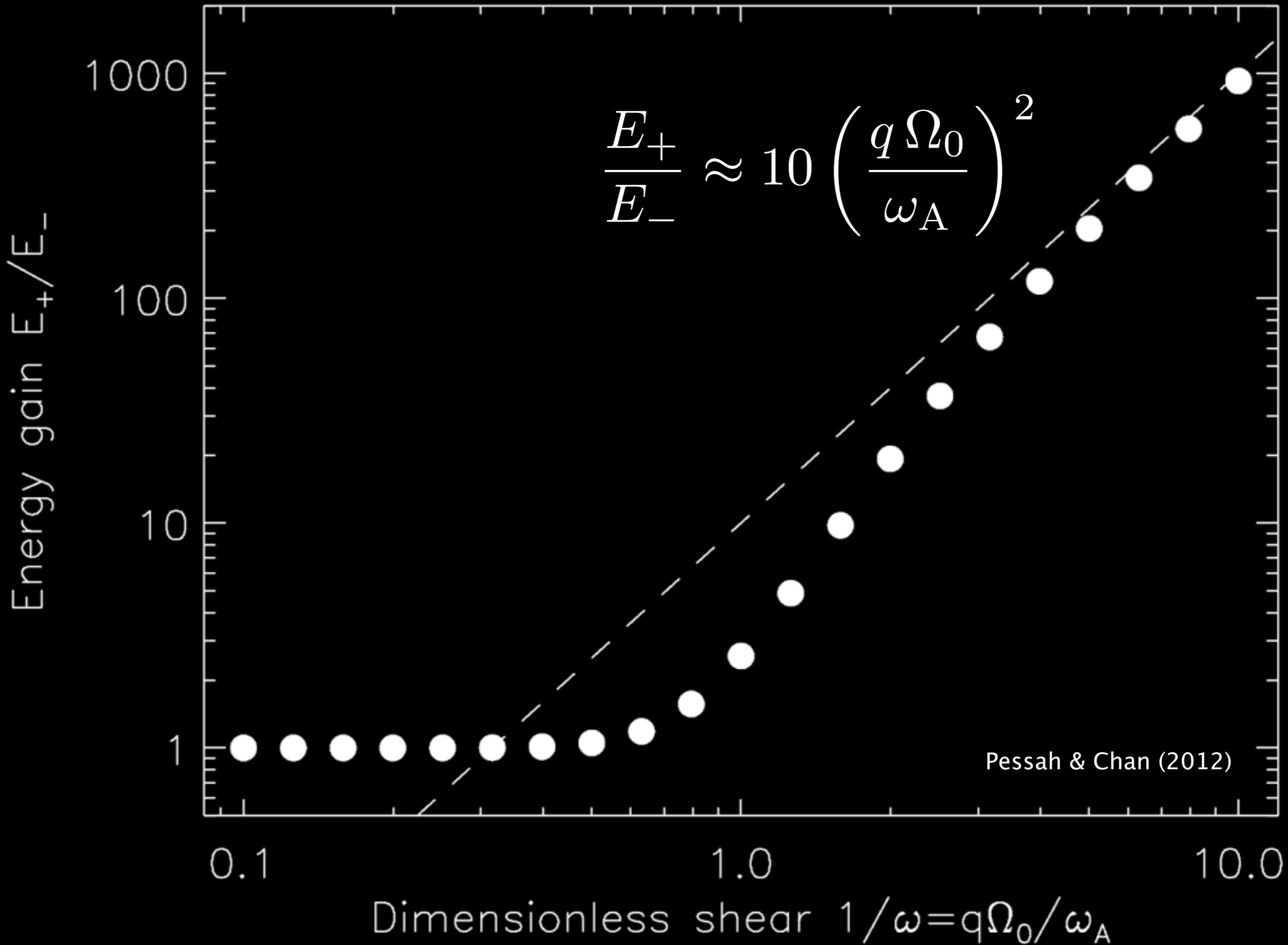






Pessah & Chan (2012)





# Conclusions & Pending Issues

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- ✦ It is possible to generate **magnetic energy without** generating **much stress** in the boundary layer
- ✦ The energy gain is **described** by  $\frac{E_+}{E_-} \approx 10 \left( \frac{q \Omega_0}{\omega_A} \right)^2$
- ✦ **"Consistent"** with simulations
- ✦ Something important remains to be understood!
- ✦ What is the mechanism for angular momentum transport when the **MRI is not active**? Belyaev, Rafikov, & Stone, 2012
- ✦ How does this translate into a **model for**  $T_{r\phi}(d\Omega/dr)$  ?